



MANUAL NO. 25  
SOFTWARE VERSION  
1.8 and HIGHER

# Model ETR-9200 AUTOMATIC TUNING SMARTER LOGIC<sup>®</sup> Controller



INSTRUCTION MANUAL

# INSTRUCTION MANUAL FOR ETR-9200



## CONTENTS

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### Section 1: INTRODUCTION

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This manual contains information for the installation and operation of the Ogden Model ETR-9200 auto-tuning micro-processor based controller.

Ease of use is an essential feature on this versatile controller. Three touch keys are used to select sensor type, control mode, control parameters, alarm mode, degree C/F, auto-manual mode, and to lock the parameters from the prevention of unauthorized tampering. Two large 4-digit displays show process and set point values at a glance. Precise 14 slope sensor linearization, self-diagnostic capability, cold junction compensation and 3-mode PID calculations are automatically executed by the single chip microprocessor. The wide selection of parameters, values, sensor types, set points, control modes, alarm modes, degrees C/F and

security codes are held in a non-volatile memory and retained for ten years if the unit is left unpowered. Batteries are not necessary.

The auto-tuning function determines the correct proportional band, rate and reset values to provide accurate control with minimal overshoot and temperature oscillation. This is accomplished without the need for expensive and time consuming procedures for set-up of control parameters. In case of a power failure or temporary shutdown, the instrument retains the correct parameters. This instrument also has manual override capabilities that allow the operator to bypass the auto-tuning parameters. Required fine tuning adjustments can then be made.

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#### **WARNING!**

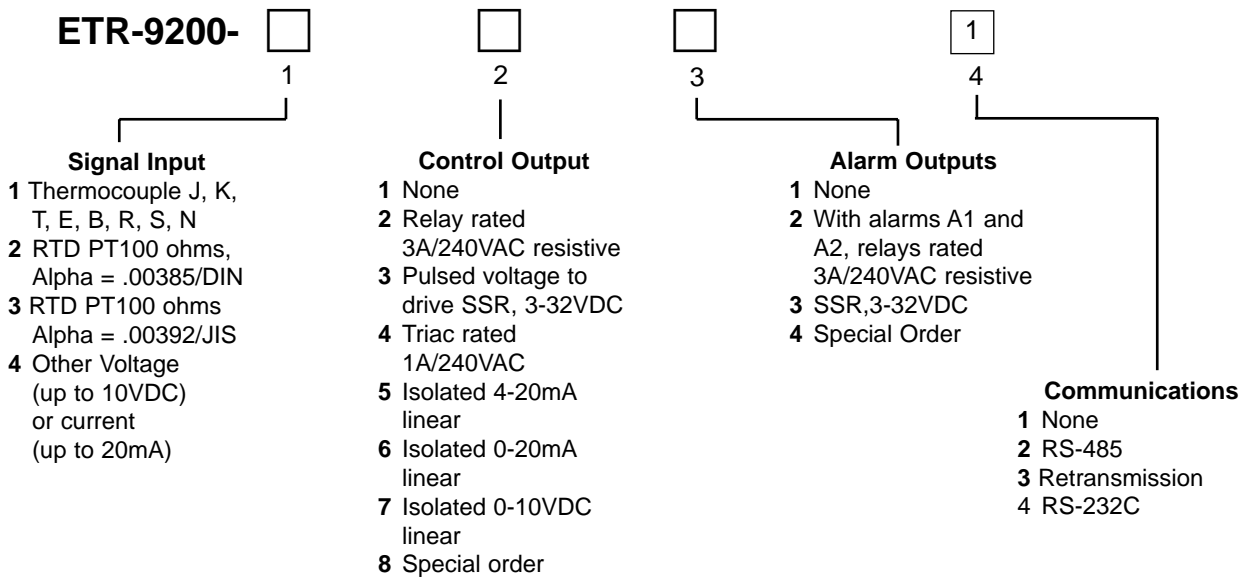
Failure of devices, such as the thermocouple-RTD sensor, heater output relay or temperature control can result in severe damage to a product while in process, melting of the heater or a damaging fire. An over-temperature protection device must be installed in your process that will remove all power from the heating circuit if the above failure occurs. We recommend that this device be classified as a safety control and carry FM, U.L. and CSA Listing or Certification. Failure to install high-limit temperature control protection where a potential hazard exists, could result in damage to equipment and property, and fatal injury to personnel.



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## Section 2: CATALOG NUMBERING SYSTEM



**Example:**

**ETR-9200-1221**

- Thermocouple type\*  
J, K, T, E, B, R, S, N
- Relay Output
- With Alarm Option

\* NOTE: True universal input can be re-programmed in field

**NOTE:** If a low voltage power source is used, place a number "3" before the Signal Input for 20-32VAC/VDC operation.

### Maximum Temperature Ranges:

Sensor	Input Type	Max. Range F°	Sensor Accuracy F°	Max. Range C°	Sensor Accuracy C°
J	Iron/Constantan	-58 to 1832°F	±3.6°F	-50 to 1000°C	±2°C
K	Chromel/Alumel	-58 to 2500°F	±3.6°F	-50 to 1370°C	±2°C
T	Copper/Constantan	-454 to 752°F	±3.6°F	-270 to 400°C	±2°C
E	Chromel/Constantan	-58 to 1382°F	±3.6°F	-50 to 750°C	±2°C
B	Pt-30%RH/Pt-6%RH	32 to 3272°F	±5.4°F	0 to 1800°C	±3°C
R	Pt-13%RH/Pt	32 to 3182°F	±3.6°F	0 to 1750°C	±2°C
S	Pt-10%RH/Pt	32 to 3182°F	±3.6°F	0 to 1750°C	±2°C
N	Nicrosil/Nisil	-58 to 2372°F	±3.6°F	-50 to 1300°C	±2°C
RTD	PT 100 ohms (DIN)	-328 to 752°F	±0.72°F	-200 to 400°C	±0.4°C
RTD	PT 100 ohms (JIS)	-328 to 752°F	±0.72°F	-200 to 400°C	±0.4°C
Linear	4 - 20 mA	-1999 to 9999	±0.05%	-1999 to 9999	±0.05%
Linear	0 - 20 mA	-1999 to 9999	±0.05%	-1999 to 9999	±0.05%
Linear	0 - 1 VDC	-1999 to 9999	±0.05%	-1999 to 9999	±0.05%
Linear	0 - 5 VDC	-1999 to 9999	±0.05%	-1999 to 9999	±0.05%
Linear	1 - 5 VDC	-1999 to 9999	±0.05%	-1999 to 9999	±0.05%
Linear	0 - 10 VDC	-1999 to 9999	±0.05%	-1999 to 9999	±0.05%

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### Section 3: SPECIFICATIONS

<b>Line Voltage:</b>	90-264VAC, 50-60Hz, 20-32VAC/DC optional	<b>Dimensions:</b>	Front Panel H - 1 $\frac{1}{8}$ " (48mm) W - 1 $\frac{1}{8}$ " (48mm) D - 3 $\frac{3}{8}$ " (86mm) Depth Behind Panel: 2 $\frac{7}{8}$ " (73mm)
<b>Consumption:</b>	Less than 5VA.	<b>Panel Cutout:</b>	1 $\frac{25}{32}$ " x 1 $\frac{25}{32}$ " (45 x 45mm)
<b>Input:</b>	Thermocouple Type: J, K, T, E, B, R, S, N RTD 2 or 3 wire PT-100 DIN @ = .00385 or JIS @ = .00392 0 – 10VDC, 0 - 20mA	<b>Proportional Band:</b>	0 - 360°F (0 - 200°C)
<b>Linear Voltage Input Impedance:</b>	100k ohms	<b>Integral (Reset):</b>	0 - 3600 seconds
<b>Cold Junction Compensation:</b>	.1C/C ambient typical	<b>Derivative (Rate):</b>	0 - 1000 seconds
<b>Sensor Break Protection:</b>	Operator selectable	<b>Ramp Rate:</b>	0- 99.99°F (0 - 55.55°C) /minute
<b>External Resistance:</b>	100 ohms max.	<b>Dwell:</b>	0 - 9999 minutes
<b>Sample Rate:</b>	5 samples per second	<b>On-Off:</b>	Adjustable hysteresis
<b>Accuracy:</b>	±.1%, ±least significant digit	<b>Proportional Cycle Time:</b>	0 - 99 seconds
<b>Normal Mode Rejection:</b>	60db	<b>°F/°C:</b>	External keypad selectable
<b>Common Mode Rejection:</b>	120db	<b>Linearization:</b>	Software driven
<b>Operating Ambient for Rated Accuracy:</b>	14 - 120°F (-10 - 50°C)	<b>Outputs:</b>	Heating (and cooling) or alarms
<b>Storage Temperature:</b>	-4 - 160°F (-20 - 70°C)	<b>Output Modules:</b>	
<b>Humidity:</b>	5 - 90% RH (non-condensing)	– <b>Current Output:</b>	4-20mA isolated, max. load 500 ohms
<b>Insulation:</b>	20M ohms min. (500VDC)	– <b>Voltage Output:</b>	0 - 10V isolated, minimum impedance 500K ohms
<b>Breakdown:</b>	2000V (AC), 50/60Hz, 1 minute	– <b>Pulsed Voltage:</b>	24VDC, unisolated Max. current 20mA
<b>Shock:</b>	200m/s <sup>2</sup> (20g)	– <b>Relay:</b>	3A/240V, resistive load for heating, 2A/240V, resistive load for alarm
<b>Weight:</b>	4 oz. (110 grams)	<b>Control Actions:</b>	Heating (relay closed on temperature rise) or cooling (relay open on temperature rise) front panel selectable
<b>EMC Emission:</b>	EN50081-1, EN61326, (EN55011 class B, EN61000- 3-2, EN61000-3-3)		
<b>EMC Immunity:</b>	EN50082-2, EN61326 (EN61000-4-2, EN61000-4-3, EN61000-4-4, EN61000-4-5, EN61000-4-6, EN61000-4-11)		

#### NON-VOLATILE MEMORY

Retains process parameters when power is off

#### EXTERNAL LOCKOUT CODE

- Prevents accidental or unauthorized changes

#### PROCESS DISPLAY

- Process display updated 5 times per second
- Menu and error codes

#### STATUS INDICATORS

- Output and alarm condition

#### 3 PUSHBUTTONS

- For ease of control set-up



#### NEMA 4X/IP65 FRONT PANEL

- Water and corrosion resistant

#### AUTOMATIC TUNING

- Eliminates complicated and time consuming manual tuning procedures
- Smarter Logic practically eliminates overshoot and temperature variations
- Universal input

#### SET VALUE DISPLAY (SV)

- All control parameters and set point displayed
- Output Percentage
- \* Calibration parameters

## Section 4: INSTALLATION

### WARNING!



**RISK OF ELECTRIC SHOCK** - Dangerous and potentially fatal voltages are present when working on this equipment. Before installation or beginning any troubleshooting procedures, the electric power to this equipment must be disconnected and locked out as described by OSHA Standards. Units suspected of being faulty must be removed and returned to Ogden for inspection and/or repair. They contain no user serviceable components.

### WARNING!



To help minimize the possibility of fire or shock hazards, do not expose this instrument to rain or excessive moisture. This control is not to be used in hazardous locations as defined in Articles 500 and 505 of the National Electric Code.

### CAUTION!



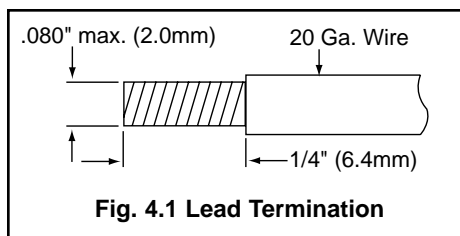
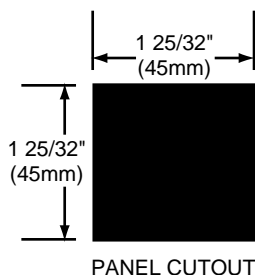
Do not use this instrument in areas subject to hazardous conditions such as excessive shock, vibration, dirt, moisture, corrosive gases or oil. The ambient temperature of the areas should not exceed the maximum rating specified in Section 3, on previous page.

### Unpacking:

Upon receipt of the shipment remove the instrument from the carton and inspect the unit for shipping damage. If any damage due to transit is noticed, report and file a claim with the carrier. Write down the model number, serial number, and date code for future reference when corresponding with our service center. The serial number (S/N) and date code (D/C) are located inside the control.

### Mounting:

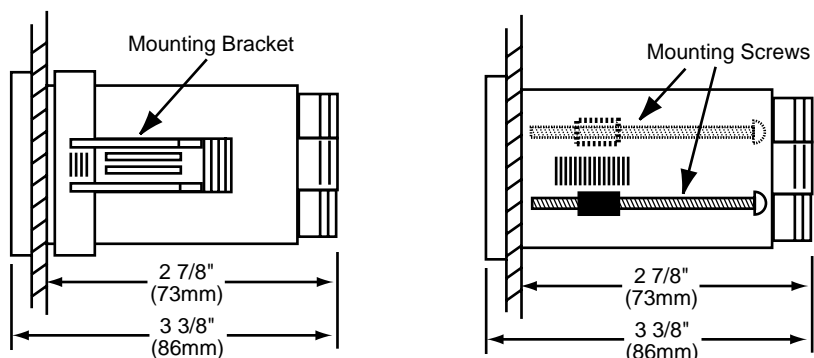
Make panel cutout to dimensions shown below right. Insert the controller into the panel cutout. The maximum panel thickness is  $\frac{1}{8}$ " (3.2mm).



### Wiring Precautions:

- Before wiring, verify the label for correct model number and options.
- Care must be taken to ensure that maximum voltage ratings specified in Section 3 on previous page are not exceeded.
- It is recommended that power to these instruments be protected by fuses or circuit breakers rated at the minimum value possible.
- All units should be installed inside a suitably grounded metal enclosure to prevent live parts being accessible to human hands and metal tools.
- All wiring must conform to appropriate standards of good practice, national and local codes and regulations. Wiring must be suitable for the maximum voltage, current, and temperature ratings expected in the system.
- Only "stripped" leads should be used for thermocouple connections to prevent compensation and resistance errors.
- Take care not to over-tighten the terminal screws.
- Unused control terminals should not be used as jumper points as they may be internally connected, causing damage to the unit.
- Verify that the ratings of the output devices and the inputs as specified on page 3 are not exceeded.
- Electric power in industrial environments contains a certain amount of noise in the form of transient voltages and spikes. This electrical noise can enter and adversely affect the operation of microprocessor-based controls. For this reason we strongly recommend the use of shielded thermocouple extension wire which connects from the sensor to the controller. This wire is a twisted-pair construction with foil wrap and drain wire. The drain wire is to be attached to earth ground at the sensor end only. We carry both type J and type K in our stock.

**NOTE:** The use of motor starters in place of magnetic contactors should be avoided. They have very large inductive loads that can damage the controller's relay.



**Fig. 4.2 Mounting Diagram**

### Power Wiring:

Connect terminals as shown in Figure 4.3. The power switch S1 and Fuse F1 are included for illustrative purpose only. Refer to Figures 4.4, 4.5, 4.6, 4.7, 4.8, 4.9, and 4.10 on the following pages for sample wiring diagrams.

### Input Wiring:

Connect the appropriate sensor to terminals 12, 13, 14, 15 or 16 as illustrated in Figure 4.3. Verify that the instrument is selected for the correct sensor and the correct polarity is observed at both the sensor-end and instrument-end of the cable. Do not run sensor cables in the same conduit or wiring trough as the power lines, because the low level signal is noise sensitive.

When wiring the thermocouple, check the thermocouple and extension wire (compensating cable) to make sure they conform to the appropriate thermocouple type specified by the instrument. Extension wires must be the same alloy and polarity as the thermocouple. The total lead resistance should not exceed 100 ohms for accurate measurements. One hundred ohms of lead resistance will introduce a 1°F (0.5°C) error.

For wiring 3 wire RTD (Resistance Temperature Detector) all leads connecting the RTD to the controller must be the same gauge and material. If the RTD is a 3 wire device, install the two common wires of the RTD to terminals 13 and 14. If a 2 wire RTD is to be used, install a jumper between terminals 13 and 14.

See page 22 for instructions to re-range the input to volts, milli-volts or milli-amps.

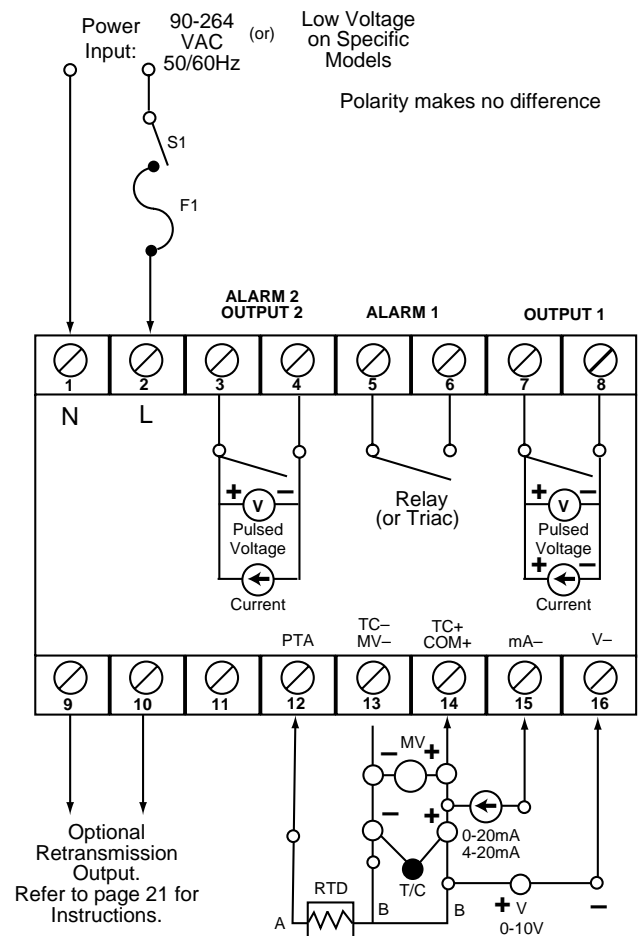


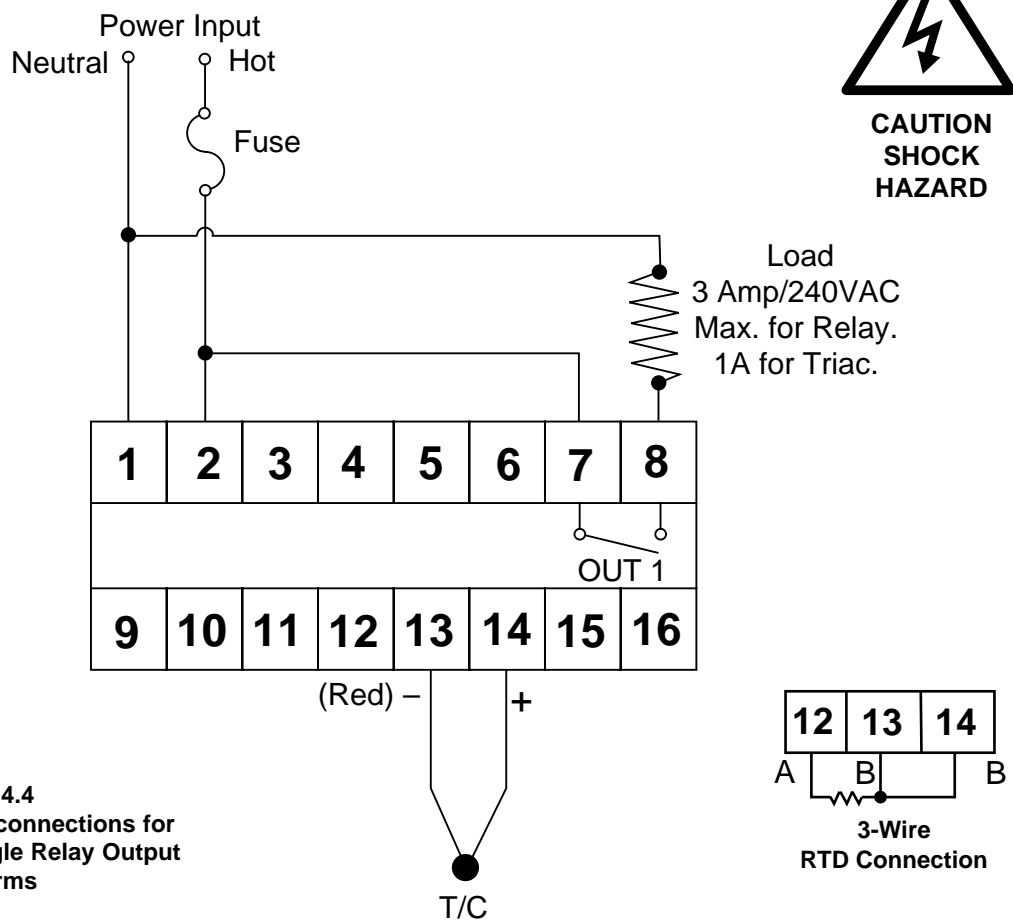
Figure 4.3 Rear Terminal Connections

Table 4.1 International Thermocouple Cable Color Codes

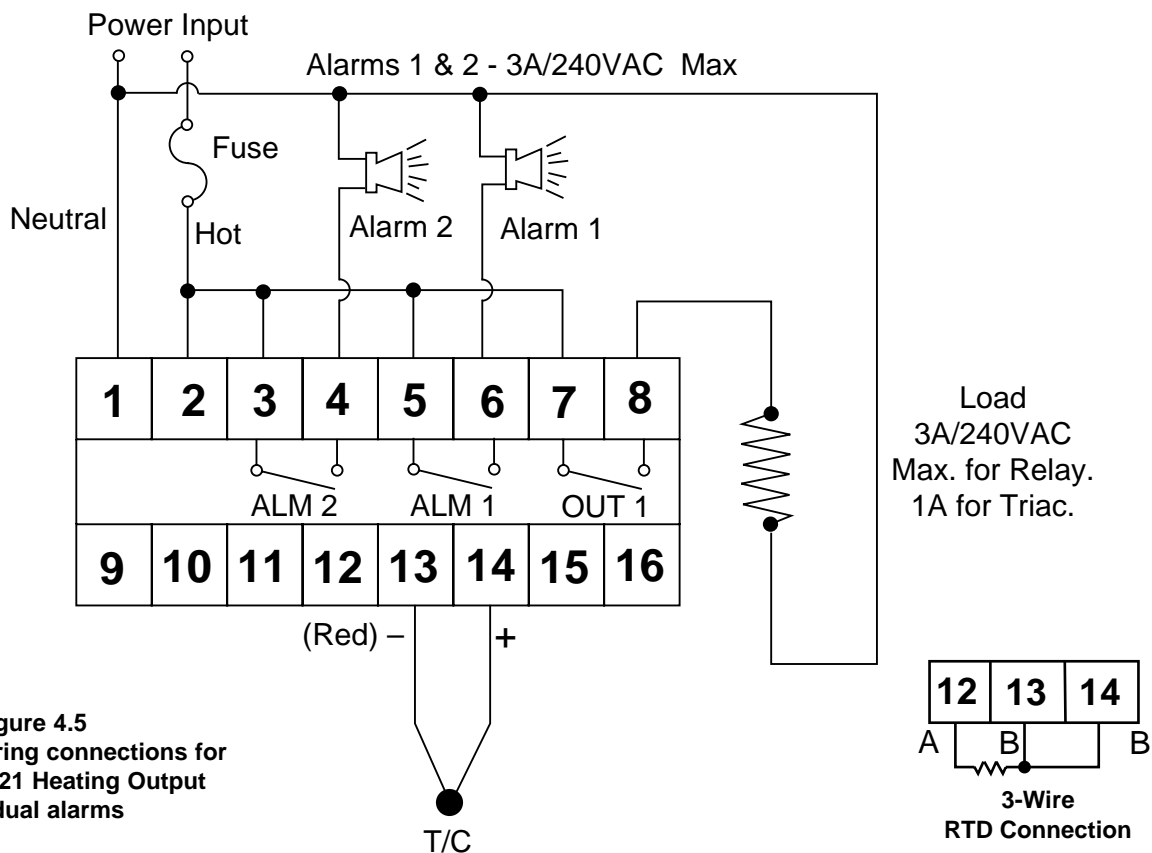
Thermocouple Type	Cable Material	American ANSI	British BS 1843	German DIN 43710	French NFE 18001
J	Iron/Constantan	+ white - red * black	+ yellow - blue * black	+ red - blue * blue	+ yellow - black * black
K	Chromel/Alumel	+ yellow - red * yellow	+ brown - black * red	+ red - green * green	+ yellow - purple * yellow
T	Copper/Constantan	+ blue - red * blue	+ white - blue * blue	+ red - brown * brown	+ yellow - black * black
R S	Platinum/Rhodium	+ black - red * green	+ white - blue * green	+ red - white * white	+ yellow - green * green
B	Platinum/Rhodium	+ grey - red * grey		+ red - grey * grey	

\* Color of overall sheath

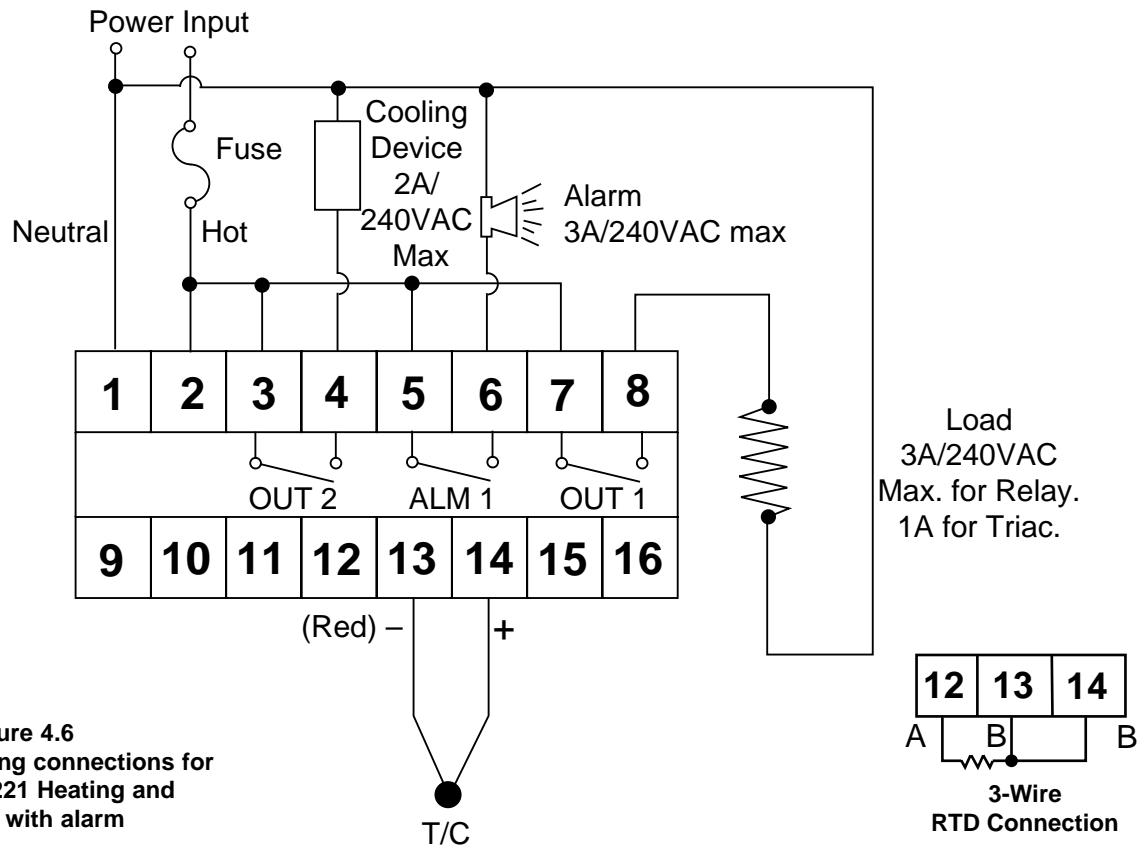
## Typical Wiring Diagrams



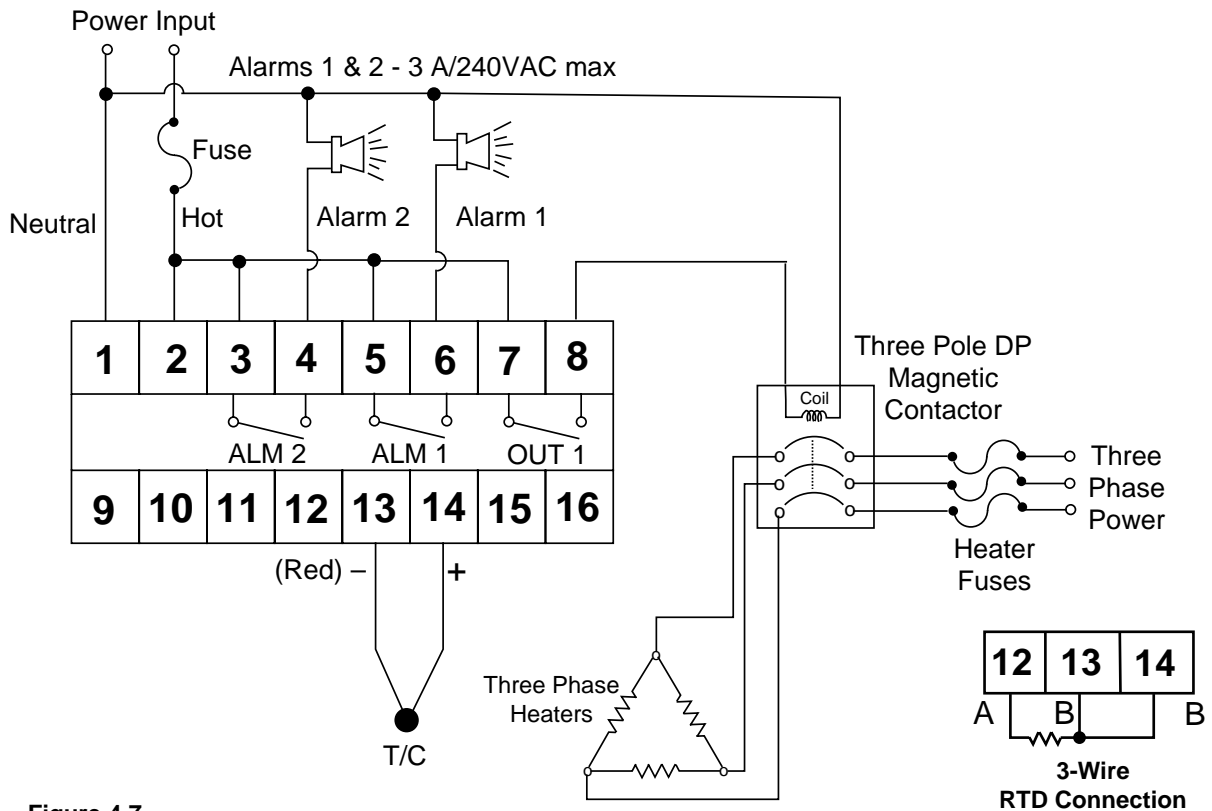
**Figure 4.4**  
Example of wiring connections for  
ETR-9200-1211 Single Relay Output  
No Alarms



**Figure 4.5**  
Example of wiring connections for  
ETR-9200-1221 Heating Output  
with dual alarms



**Figure 4.6**  
Example of wiring connections for  
ETR-9200-1221 Heating and  
Cooling with alarm



**Figure 4.7**  
Example of wiring connections for  
ETR-9200-1221 with three phase  
Delta heater load

**NOTE:** The use of motor starters in place of magnetic contactors should be avoided. They have very large inductive loads that can damage the controller's relay.



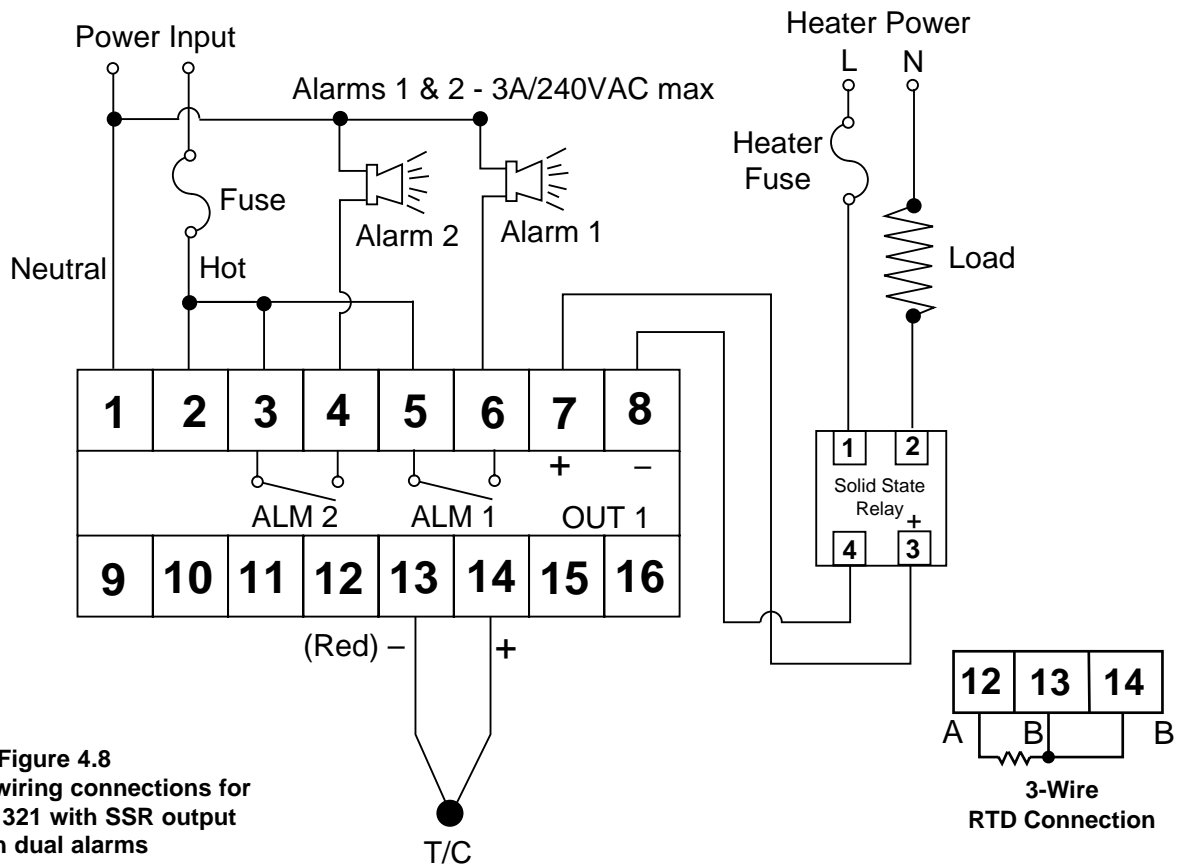


Figure 4.8  
Example of wiring connections for  
ETR-9200-1321 with SSR output  
with dual alarms

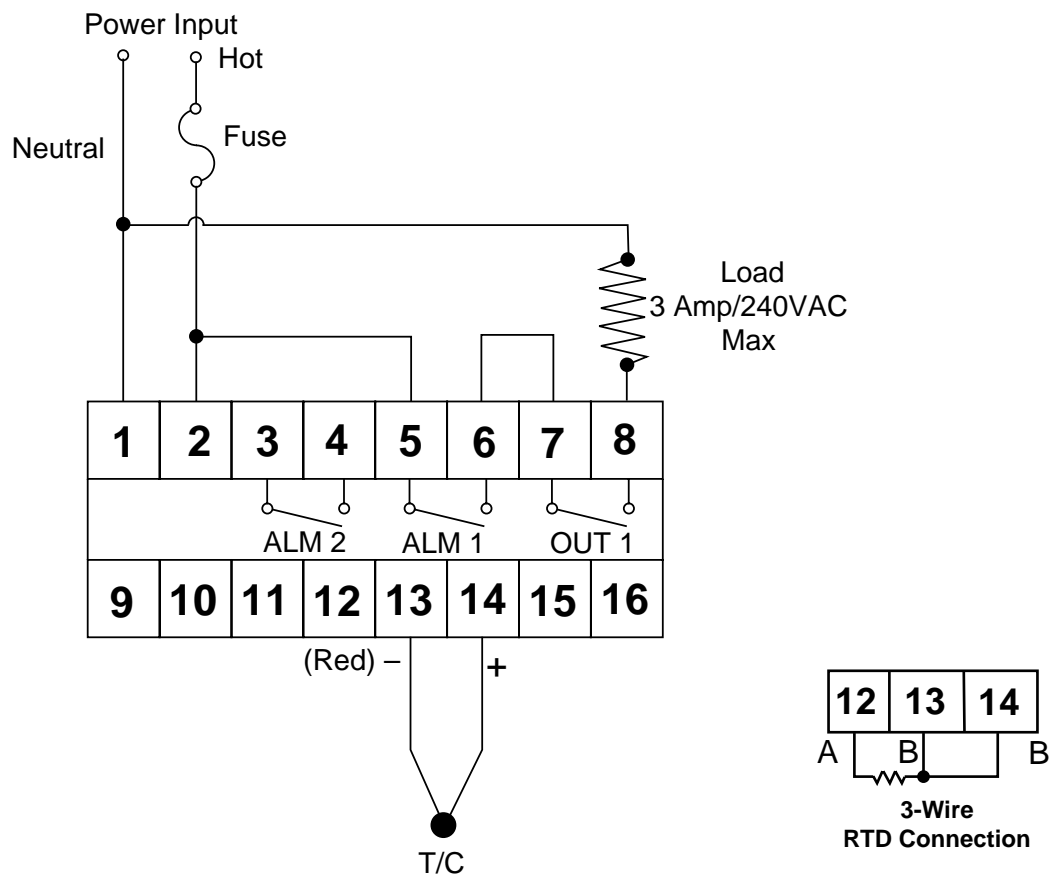
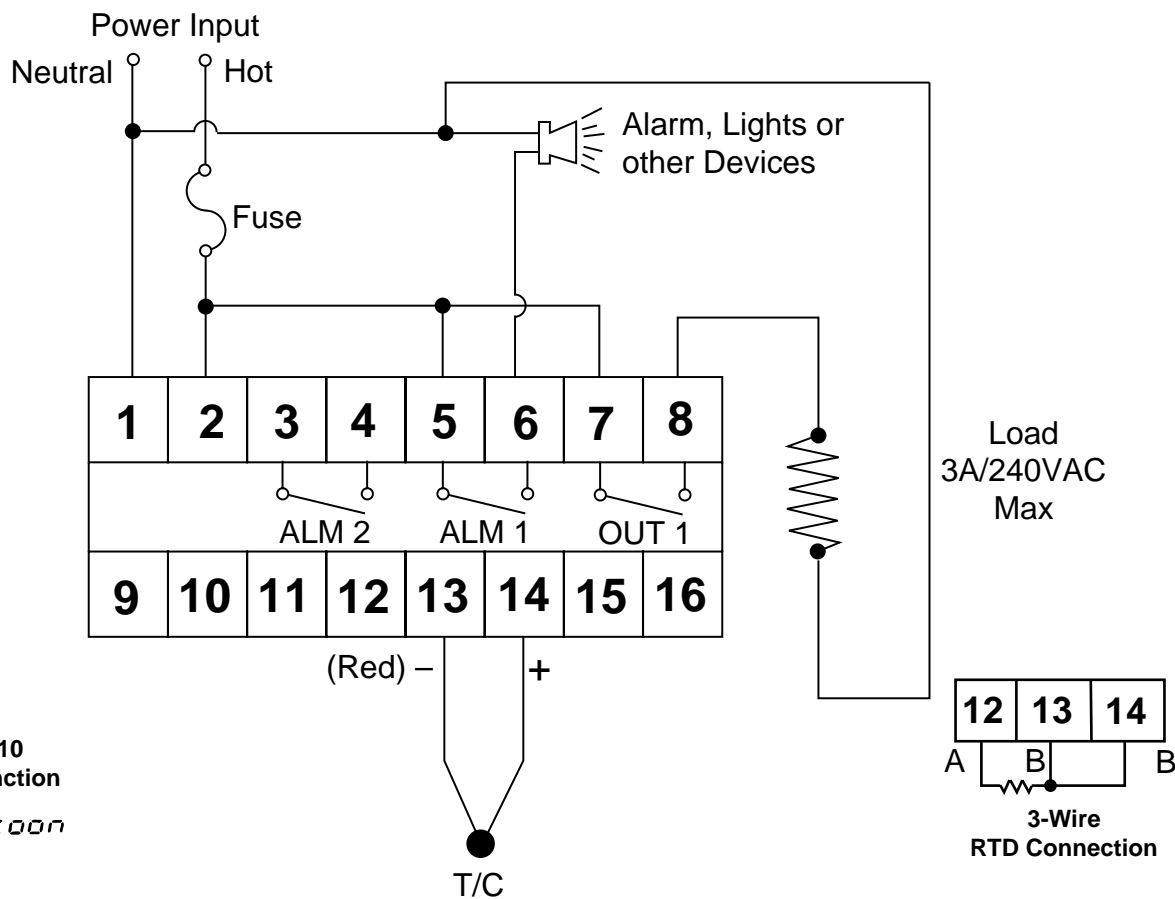


Figure 4.9  
Ramp and Soak  
RTD = 100°F



**Fig. 4.10**  
**Dwell Function**  
*ALSF = toon*

### Output Wiring:

Four different types of output devices can be used from output one. Relay, current, voltage and pulsed voltage provide a variety of control applications. Verify that the output device is correctly selected to meet your application requirements and make certain the ratings of the output devices are not exceeded before wiring the system.

The external connections depend on what type of output is installed. Pulsed voltage output is not isolated from the internal circuits of the instrument.

### Sensor Placement

Proper sensor placement can eliminate many problems in a control system. The probe should be placed so that it can detect any temperature change with minimal thermal lag. In a process that requires fairly constant heat output, the probe should be placed close to the heater. In processes where the heat demand is variable, the probe should be closer to the work area. Some experimenting with probe location is often

required to find this optimum position.

In a liquid process, addition of a stirrer will help to eliminate thermal lag. Since the thermocouple is basically a point measuring device, placing more than one thermocouple in parallel will provide an average temperature reading and produce better results in most air heated processes.

Proper sensor type is also a very important factor in obtaining precise measurements. The sensor must have the correct temperature range to meet the process requirements. In special processes the sensor might have to have different requirements such as leak-proof, anti-vibration, antiseptic, etc.

Standard thermocouple sensor limits of error are  $\pm 4$  degrees F ( $\pm 2$  degrees C) or 0.75% of sensed temperature (half that for special) plus drift caused by improper protection or over-temperature occurrence. This error is far greater than controller error and cannot be corrected at the sensor except by proper selection and replacement.

When installation has been completed, the clear protective film can be removed from the faceplate.

## Section 5: OPERATION

**Table 5.1 Keypad Operation**

TOUCHKEYS	FUNCTION	DESCRIPTION
	Scroll Key	Advances the display to the desired parameter. Parameters advance continuously and cyclically by pressing this key.
	Up Key	1. Increases the value of a numerical parameter. 2. Selects a desired item in the engineering level.
	Down Key	1. Decreases the value of a numerical parameter. 2. Selects a desired item in the engineering level.

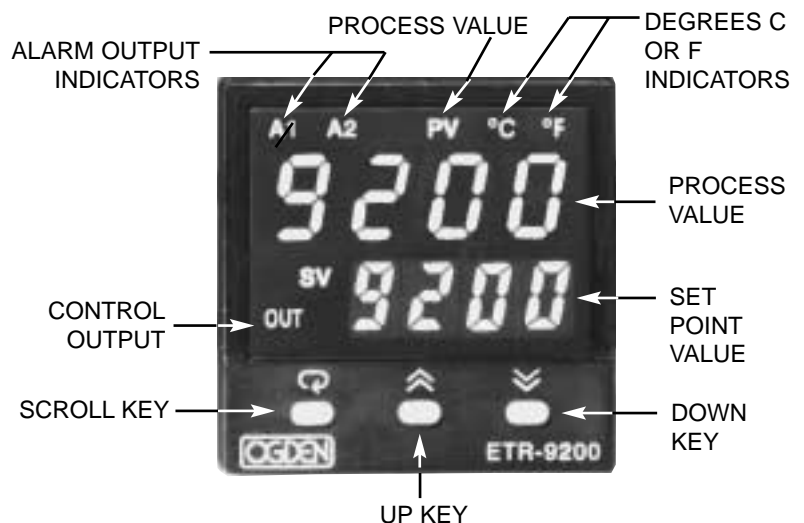
To change the parameter, tap the or key quickly. This will brighten the individual digit of the display. Once the desired digit is brighter, simply hold down the or key to increase or decrease the value.

Press  longer than 4 seconds	Long Scroll/ Enter Key	1. Selects the parameters in higher security level. 2. Actuates the selected program when in engineering level.
Press  and	Reverse Scroll/ Calibration Verification Key	1. Selects the parameters in a reverse direction during parameter scrolling. 2. Verifies the display accuracy for various input types during calibration.
Press  and  longer than 4 seconds	Lock Key	Disables keypad operation to protect all parameters from being tampered with.
Press  and	Engineering Level Key	Selects the Engineering level. Scrolls through the Engineering Programs.
Press  and	Reset (Exit) Key Unlock Key	1. Resets the control to its normal status. 2. Unlocks keypad operation. 3. Exits the engineering level program. 4. Stops the Autotuning function.
Press  and  longer than 4 seconds	Autotune Key	Starts the Autotune function.

### ETR-9200 TOUCH KEY DESCRIPTIONS:

To move from one level of parameters to another. Scroll to the end of the level. Hold down the key, the display will flash, once the display stops flashing, release the key.

To return from any parameter to the process and set point values, press the and keys simultaneously.



# PROCESS VALUE SET POINT VALUE

Table 5.2 Control Function  
and Display Flow Chart  
(OPERATOR LEVEL)

Security  
Level 0

Security  
Level 1

Security  
Level 2

ASPI  
rAnP  
oFSt  
ASP2



Short Scroll advances step by step  
through parameters in forward direction

Short Scroll returns  
to PV/SV



Hold until display  
stops strobing (4 seconds)

SH.F  
Pb  
t1  
t2  
AhY1  
AhY2  
hYST  
Addr



Short Scroll advances step by step  
through parameters in forward direction



Views parameters step by step  
in reverse order

Short Scroll returns to PV/SV



Hold until display  
stops strobing (4 seconds)

LoSC  
hiSC  
PL1  
PL2  
inPt  
unit  
rESo  
Con.A  
A1.nd  
A1.SF  
A2.nd  
A2.SF  
CYC  
CCYC  
C.Pb  
d-b



Short Scroll advances step by  
step through parameters in  
forward direction

## POWER APPLIED:

1) 9200/ 91.8 /Software Version  
displayed for 4 seconds.

2) LED check/all LED segments  
lit for 4 seconds



Exits parameters and returns  
to process and set point values.

Engineering Level can be entered  
at any time by pressing the and keys. (See page 14.)

NOTE: Control will return to Process  
Value in 25 seconds if no entry is made.

Short Scroll returns to PV/SV



**Table 5.3 Index Code (Menu) Descriptions (OPERATOR LEVEL)**

Security Levels	Display Code:	Description:	Adjusting Range:	Default Setting:
0	<b>SV</b>	Set point Value of Control	Low scale to high scale value	212
	<b>ASPI</b>	Alarm 1 Set Point Value. Dwell Time <i>RTSF = 1000 or 1000F/Minutes</i>	Trip Point within High/Low scale or 0 - 9999 minutes (for Dwell Time)	18°F (10°C)
	<b>rANP</b>	Ramp Rate	0 - 99.99°F/minute (0 - 55.55°C/minute)	0.00
	<b>oFSI</b>	Offset Value for Manual Reset (Integral Time TI = 0)	0 - 100% Only functional if Integral is set to 0.	0.0
	<b>ASP2</b>	Alarm 2 Set Point Value	Trip Point within High/Low scale	18°F (10°C)
1	<b>SHIF</b>	Display Shift	-199° to 199°F (-111 - 111°C) (Refer to page 21)	0
	<b>Pb</b>	Proportional Band of Output 1	0 - 360°F (0-200.0 °C) 0: for ON-OFF control (Refer to Page 17)	18°F (10.0°C)
	<b>t<sub>i</sub></b>	Integral (Reset) Time of Output 1	0 - 3600 seconds	120
	<b>t<sub>d</sub></b>	Derivative (Rate) Time of Output 1	0 - 1000 seconds	40
	<b>AHY1</b>	Hysteresis of Alarm 1	0 - 19°F (0 - 11 °C)	0
	<b>AHY2</b>	Hysteresis of Alarm 2	0 - 19°F (1 - 11 °C)	0
	<b>HYST</b>	Hysteresis of ON-OFF control	0 - 19°F (1 - 11 °C)	0
	<b>Addr</b>	Interface Address	0 - 40	0
2	<b>LoSC</b>	Low Scale of Range. Adjust for your process	Minimum value for the selected Input (INPT) to High Scale (HISC)	0
	<b>hiSC</b>	High Scale of Range. Adjust for your process	Low Scale (LOSC) to maximum value for the selected Input (INPT)	999
	<b>PL1</b>	Power Limit of Output 1	0 - 100%	100%
	<b>PL2</b>	Power Limit of Output 2	0 - 100%	100%
	<b>inPt</b>	Input Type Selection	<i>J-tC</i> = J Type T/C <i>K-tC</i> = K Type T/C <i>t-tC</i> = T Type T/C <i>E-tC</i> = E Type T/C <i>b-tC</i> = B Type T/C <i>r-tC</i> = R Type T/C <i>S-tC</i> = S Type T/C <i>n-tC</i> = N Type T/C <i>PtDn</i> PT100 DIN <i>PtJS</i> = PT100 JIS <i>4-20</i> = 4-20 mA <i>0-20</i> = 0-20 mA <i>0-1V</i> = 0 - 1V <i>0-5V</i> = 0-5V <i>1-5V</i> = 1 - 5V <i>0-10V</i> = 0 - 10V	<i>J-tC</i>
	<b>unit</b>	Display Units	<i>°C</i> = degree C <i>°F</i> = degree F <i>Pu</i> = process units (Engineering Units)	<i>°F</i>
	<b>rESo</b>	Resolution	<i>nodP</i> = No decimal point used <i>1dP</i> = 1 Digit decimal <i>2dP</i> = 2 Digit decimal (only for Linear Voltage or Current Input)	<i>nodP</i>
	<b>Con.A</b>	Control Action of Output 1	<i>dirC</i> = Direct (Cooling) Action <i>revC</i> = Reverse (Heating) Action	<i>revC</i>
	<b>Al.nd</b>	Alarm 1 Mode	<i>dVh</i> = Deviation High Alarm <i>dVLo</i> = Deviation Low Alarm <i>dBh</i> = Deviation Band High Alarm <i>dbLo</i> = Deviation Band Low Alarm <i>FSh</i> = Full Scale High Alarm <i>FSLo</i> = Full Scale Low Alrm	<i>dVh</i>
	<b>Al.SF</b>	Alarm 1 Special Function	<i>nonE</i> = No Special Function <i>lth</i> = Alarm with Latch Function <i>hol</i> = Alarm with Hold Function <i>ltho</i> = Alarm with Latch & Hold Function <i>tsOn</i> = Dwell Timer ON as Time Out <i>tsOff</i> = Dwell Timer OFF as Time Out	<i>nonE</i>
	<b>A2.nd</b>	Alarm 2 Mode	Same as Alarm Mode 1	<i>dVh</i>
	<b>A2.SF</b>	Alarm 2 Special Function	<i>nonE</i> = No Special Function <i>lth</i> = Alarm w/Latch <i>ool</i> = Output 2 cooling <i>hol</i> = Alarm w/Hold <i>ltho</i> = Alarm w/Latch & Hold	<i>nonE</i>
	<b>CYC</b>	Proportional Cycle Time of Output 1	0 - 99 Seconds, 0 for Linear current/voltage output	20 For Relay Output
	<b>CCYC</b>	Cooling Cycle Time	0 - 99 Seconds, 0 for Linear current/voltage output	20 For Relay Output
	<b>CPb</b>	Cooling P Band	0 - 360°F (0 - 200°C)	18°F (10.0°C)
	<b>d-b</b>	Dead Band for pB and CPB	-199 - 199°F (-111 - 111°C)	0

Table 5.4 Parameter Record Sheet (OPERATOR LEVEL)

CONTROL NO.	DATE	PARAMETER					
		<b>SV</b> SET POINT VALUE					
		<b>ASPI</b> ALARM SET POINT 1					
		<b>rAnP</b> RAMP RATE					
		<b>oFSt</b> OFFSET					
		<b>ASP2</b> ALARM SET POINT 2					
		<b>SHiF</b> DISPLAY SHIFT					
		<b>Pb</b> PROPORTIONAL BAND/HEAT					
		<b>t<sub>i</sub></b> INTEGRAL TIME					
		<b>t<sub>d</sub></b> DERIVATIVE TIME					
		<b>RhY.1</b> HYSTERESIS ALARM 1					
		<b>RhY.2</b> HYSTERESIS ALARM 2					
		<b>hYSt</b> HYSTERESIS ON/OFF					
		<b>Addr</b> ADDRESS					
		<b>Lo.SL</b> LOW LIMIT OF RANGE					
		<b>hi.SL</b> HIGH LIMIT OF RANGE					
		<b>PL1</b> POWER LIMIT OUTPUT 1					
		<b>PL.2</b> POWER LIMIT OUTPUT 2					
		<b>inPt</b> INPUT TYPE					
		<b>unit</b> UNIT TYPE					
		<b>rESo</b> RESOLUTION					
		<b>Con.A</b> CONTROL ACTION					
		<b>AlAd</b> ALARM MODE 1					
		<b>AlSF</b> ALARM 1 SPECIAL FUNCTION					
		<b>A2Ad</b> ALARM MODE 2					
		<b>A2SF</b> ALARM 2 SPECIAL FUNCTION					
		<b>CYC</b> PROPORTIONAL CYCLE TIME					
		<b>CCYC</b> COOLING CYCLE TIME					
		<b>CPb</b> COOLING PROPORTIONAL BAND					
		<b>d-b</b> DEADBAND					

### Table 5.5 Engineering Level

The engineering level can be entered at any time by pressing the keys. This level contains six parameters for control configuration and options. The parameters are defined as:

**Manual Mode (hand control)** – This feature is used if the sensor fails. The control can now be used as an on-off proportional timer to control the load until a new sensor can be installed. The setting for heating or cooling is 0 - 100% of the proportional cycle time.

**Peak Process Values** – The minimum and maximum peak values of the process are indicated here.

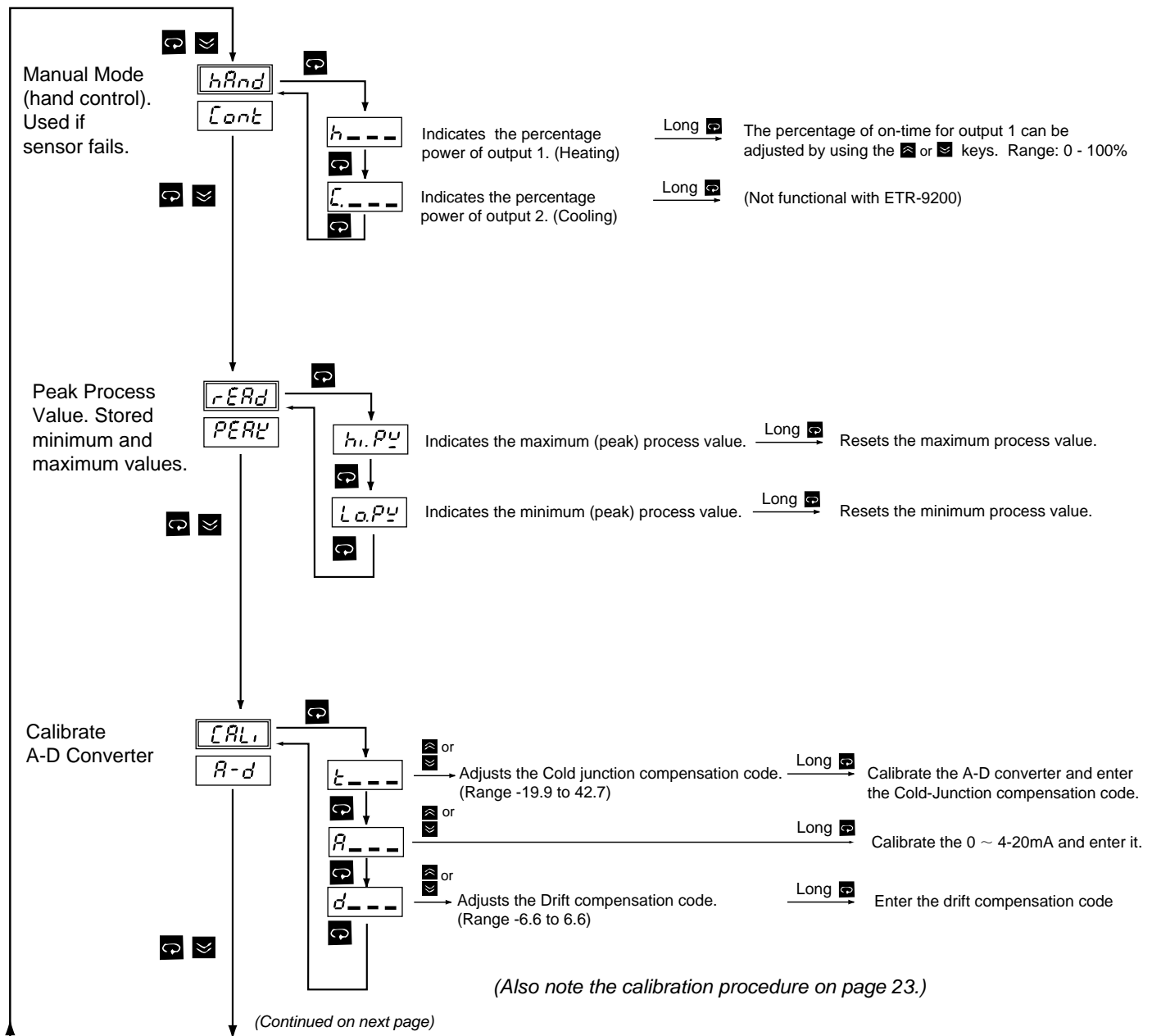
**Calibrate A-D Converter** – This parameter is used during the calibration procedure.

**Fail Safe** – This defines the status of the outputs if the sensor fails.

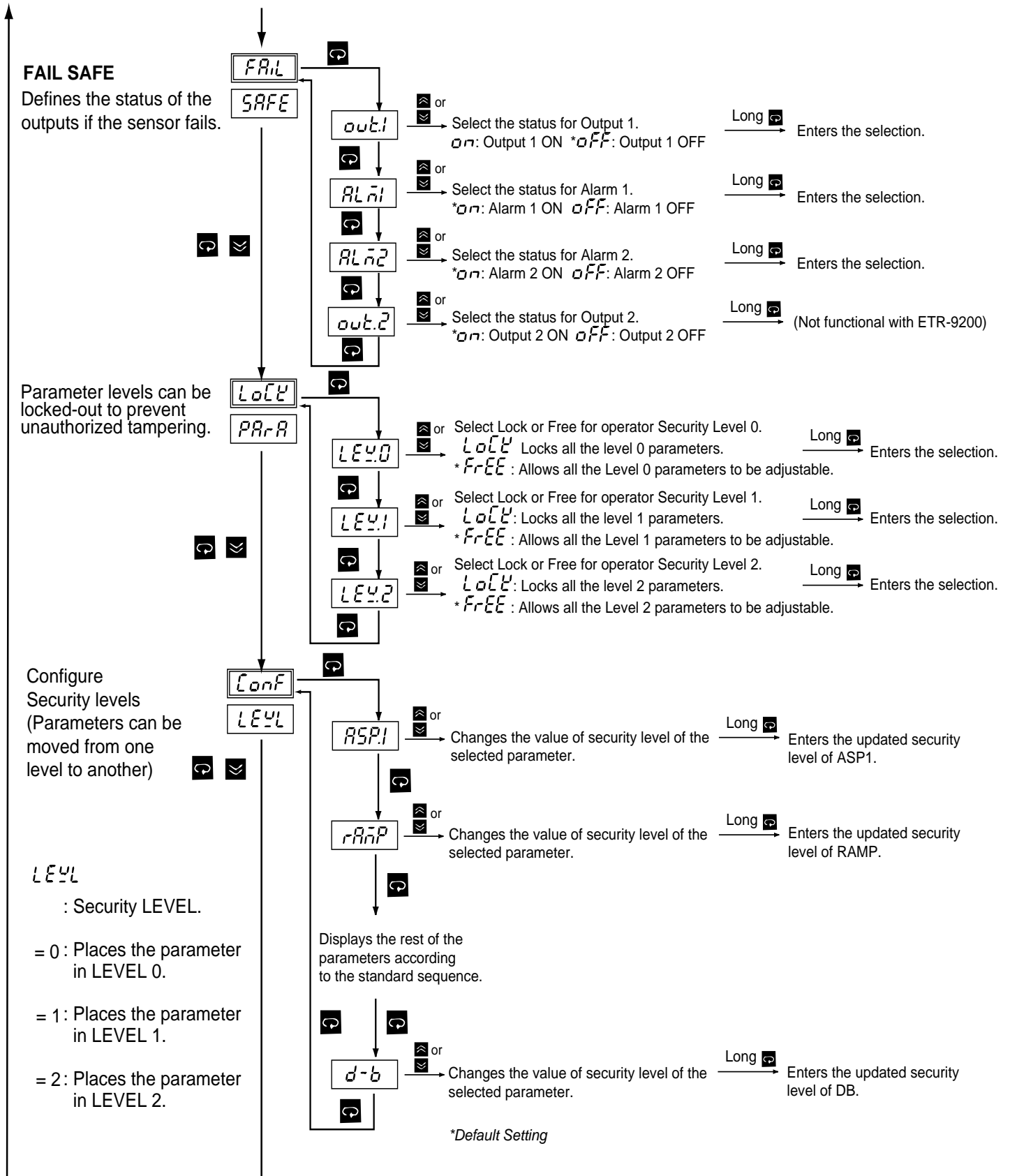
**Lock Parameters** – Levels 0, 1 or 2 in the operators level can be locked-out to prevent unauthorized tampering.

**Configuration Level** – This feature allows parameters to change levels (0, 1 or 2) in the operators level. The purpose of this is to allow only selected parameters to be adjustable and all the others to be locked-out. For example, if only the set point is to remain un-locked, all the other parameters in level 0 can be moved to level 1. Then lock out level 1 and 2.

Press the keys to exit the engineering level.



## (Engineering Level continued)



Press the keys to exit the engineering level.



## **Operator Level Parameter Definitions:**

**PV - Process Value** This is the temperature (or other process variable) as measured at the sensor. This will indicate a value within the range between the low scale (Lo.SC) and high scale value (hi.SC). This indication will read an error code if the temperature (process variable) goes out of the preset span. Note items 6 and 7 of the troubleshooting guide on page 25 for the error code descriptions.

**SV - Set Point Value** This parameter is the desired set point of the process. It can be adjusted within the range defined by the low scale (Lo.SC) and high scale value (hi.SC). The span adjustments can be used to limit the set point of the controller.

**ASP1 - Alarm 1 Set Point Value or Dwell Time** This sets the points at which alarm 1 will energize if A1.SF (alarm 1 special function) is set for an alarm function. If A1.SF is selected for the dwell timer function (toon or toof), then this becomes the timer setting in minutes. The dwell timer starts counting when the process value reaches the set point value. Note page 20 for more information.

**rAMP - Ramp Rate** This controls the heat-up and cool-down rate of the process. This setting is in degrees per minute.

**oFSE - Offset Value** This parameter is only functional if the integral time (automatic reset) is set to zero. The oFSE then functions the same as manual reset to correct the process temperature to the set point temperature. If the process temperature stabilizes below the set point, then set a positive amount of oFSE. If the process temperature stabilizes above the set point, set a negative amount of oFSE. Wait for the system to stabilize and make further adjustments as required.

**ASP2 - Alarm 2 Set Point Value** This sets the points at which alarm 2 will energize if A2.SF (alarm 2 special function) is set for an alarm function. If A2.SF is selected for cooling; the cooling cycle time, proportional band and deadband are adjusted by parameters CCyC, C.pb and d-b. ASP2 will then have no effect. Note page 20 for more information.

**ShiF - Display Shift** A value entered here will be added or subtracted from the process value. This offset can be used as a correction factor if the sensor does not read the same temperature as the item being sensed. Note page 21 for more information.

**Pb, Ei and Ed - PID Values** Proportional band, Integral (reset) and Derivative (rate) time constants. These must be set as close as possible to the process application requirements. Note page 17 for more information.

**AhY1, AhY2 - Hysteresis of Alarm 1 and Alarm 2** The values entered here define the deadbands for the alarms. The alarms will not change state until the temperature is outside of the deadband.

**hySE - Hysteresis of On-Off Control** This parameter defines the deadband when on-off control is used and PID control has been disabled. For on-off control, set

Pb, Ei and Ed to 0. The output on a relay control will not change state until the temperature is outside the deadband. Note page 17 for further information.

**Addr - Interface Address** For external communications with a computer.

**Lo.SC, hi.SC - Low/High Scale Range** These parameters are used to define the range (span) of the control. These should be set for the requirements and safety of your process. Refer to "Initial Operation" on page 17 for further information. If inputs other than thermocouples or RTDs are required, refer to page 22 for reranging directions.

**PL.1, PL.2 - Power Limit** These parameters are used to limit the output percentage of power for heating or cooling. If the control has relay or pulsed voltage outputs, then the percentage of "on" time will be decreased. The actual output levels will be decreased if the control has linear current (4-20mA) or linear voltage outputs.

**inPE - Input Type** This parameter is used to program the control to the type of input sensor used.

**uniE - Process Units** This parameter is used to set the display in degrees F, C or blank for engineering units.

**rESo - Display Resolution** This parameter is used to place a decimal point in the process and set point values. A two-place decimal point can only be set if the uniE adjustment is set to engineering units (PU).

**Con.A - Control Action of Output 1** This parameter selects heating (reverse) or cooling (direct) action for output 1.

**A1.Md, A2.Md - Alarm Mode Selection for Alarm 1 and Alarm 2** This adjustment sets the type of alarm required: deviation alarm, band alarm or process alarm. Refer to page 20 for more information.

**A1.SF - Alarm 1 Special Function** This selects special functions required for use with alarm 1. The special functions include latching alarms, hold (inhibited) function or dwell timer function. Refer to page 20 for more information on alarms.

**A2.SF - Alarm 2 Special Function** This selects special functions for alarm 2. This includes latching function, hold (inhibited) function or proportional cooling.

**CyC - Proportional Cycle Time of Output 1** This sets the proportional cycle time for output 1. This should be set according to the type of output device used. For mechanical relays, cycle times of 15 to 20 seconds are used. For solid-state relays, set this adjustment to 1 or 0. For 4-20mA or other linear outputs set this to 0.

**CCyC - Cooling Cycle Time** Only used if A2.SF (alarm 2 special function) has been set for cooling. Use the same settings as the above paragraph.

**C.Pb, d-b Cooling Proportional Band, Cooling Deadband** Only used if A2.SF (alarm 2 special function) has been set for cooling. Refer to page 22 for further information on the settings to be used for cooling output.

### Initial Operation:

When the control has been wired you can apply power. The display should indicate the model number, software version and LED lamp illumination test. The temperature (or other process variable) as measured at the sensor should be indicated by the PV display. The thermocouple is wired in reverse if the indicated temperature decreases as the temperature at the thermocouple increases. While making initial settings to configure the control, the set point should be lowered to a value (eg. 30°F) to assure the heaters will not be energized. This will allow time to make any adjustments of the parameters in the operators or engineering level.



During this initial set-up, alarm points and other settings can be made. The low limit and high limit range settings (Lo.SC) and (hi.SC) should be adjusted to your process. This sets the range (span) of the control. The set point cannot be adjusted out of this range. Generally, for plastics processing and packaging, a span of 0 - 800°F is common. If oils are used, a lower span such as 0 -300°F should be entered.

When the configuration settings have been made, you can return to the PV/SV level. Adjust the required process set point. The red "out" lamp should illuminate, indicating the heaters have been powered.

### Autotuning:

The autotune function "teaches" the controller the main characteristics of the process. It "learns" by cycling the output on and off. The process will oscillate around the set point during autotuning. Note the diagram below:

Adjust the set point to a lower value if overshoot beyond the normal process value may cause damage. The results are measured and used to calculate the optimum PID values. It should not have to be repeated on the same process. The autotune function starts by

depressing the  and  keys for 4 seconds; then release. The process value display will flash on and off indicating the control is in the autotune mode. No other adjustments can be made to the system while the control is autotuning. The control will finish autotuning by itself and the correct PID values will be entered into the control's memory.

Autotuning will not function if the control has been configured from PID to ON-OFF. For electric heating PID is usually recommended.

Autotuning may not give satisfactory results and hold a close temperature on all applications. If this occurs, you can change the PID values manually using the three charts in Figure 5.2 on the top of the next page for a guide. It is recommended to change only one parameter at a time, so the results of that change can be clearly noted.

### Adjusting PID Parameters:

The PID parameters can be reviewed by operating the scroll key and noting whether the values are reasonable or not. Examine the controller's result. Modify the PID values until the control quality is acceptable.

### ON-OFF Control:

On-off control action is recommended when continuous cycling of the load cannot be used. Examples are mechanical solenoids, large contactors and valves. For on-off control, set the following parameters to zero: proportional band; integral; derivative and offset (oFSE). The hysteresis (hySE) adjustment is now used to set the deadband. The larger the hysteresis is set, the larger the deadband will be. A large deadband will cause the contactor (or other device) to switch less often, but the process will oscillate farther from the set point. This setting is measured in degrees.

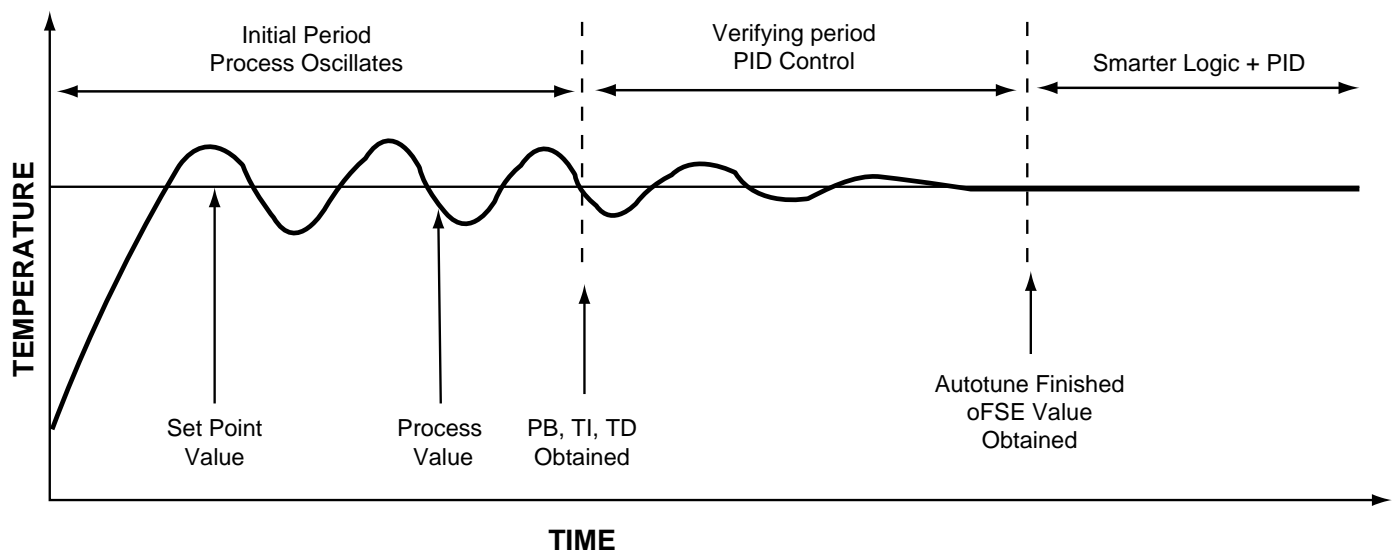


Figure 5.1 Autotuning

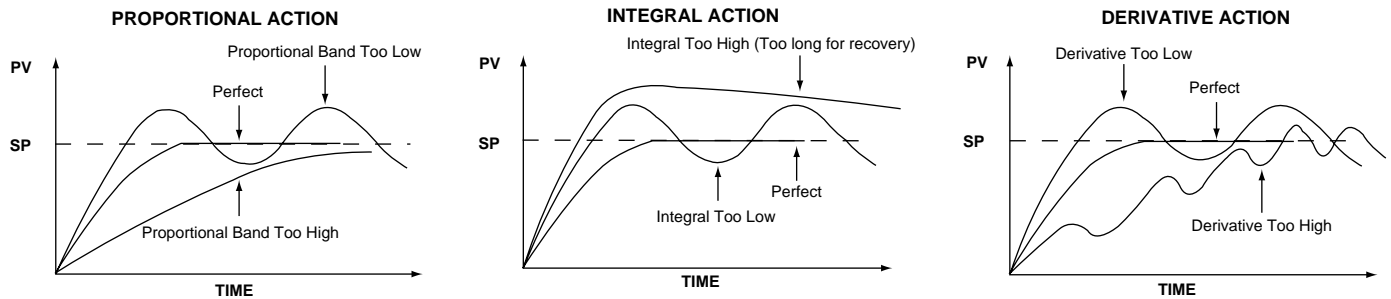


Fig. 5.2 Effects of PID Adjustment of Process Response

The proportional band (Pb) is a temperature band expressed in degrees. When the process temperature is within this band, the time proportioning function is active.

Integral action (automatic reset) corrects for offset (load error) for load variations. Anti-reset wind-up inhibition prevents integral action from occurring outside of the proportional band. Software antisaturation minimizes process oscillation when the load changes

Derivative action is adjusted to match the response time of the process and to compensate the integral action. Correct adjustment provides power output compensation for process load variations. It also minimizes overshoot and oscillations at start up or in large process upsets.

oscillations then gradually decrease the proportional band until steady cycling is observed. Record this important proportional band percentage (Pc).

Step 5: Time the period of steady cycling. Record this critical period  $T_c$ . The PID parameters are determined as:

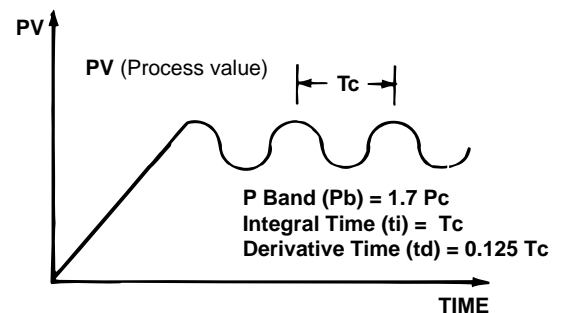


Fig. 5.3 Steady State Cycling

### Manual Tuning Procedures:

For some systems it is difficult to execute automatic tuning or the automatic tuning results are not satisfactory. The following steps can then be used for initial tuning of a three-mode control:

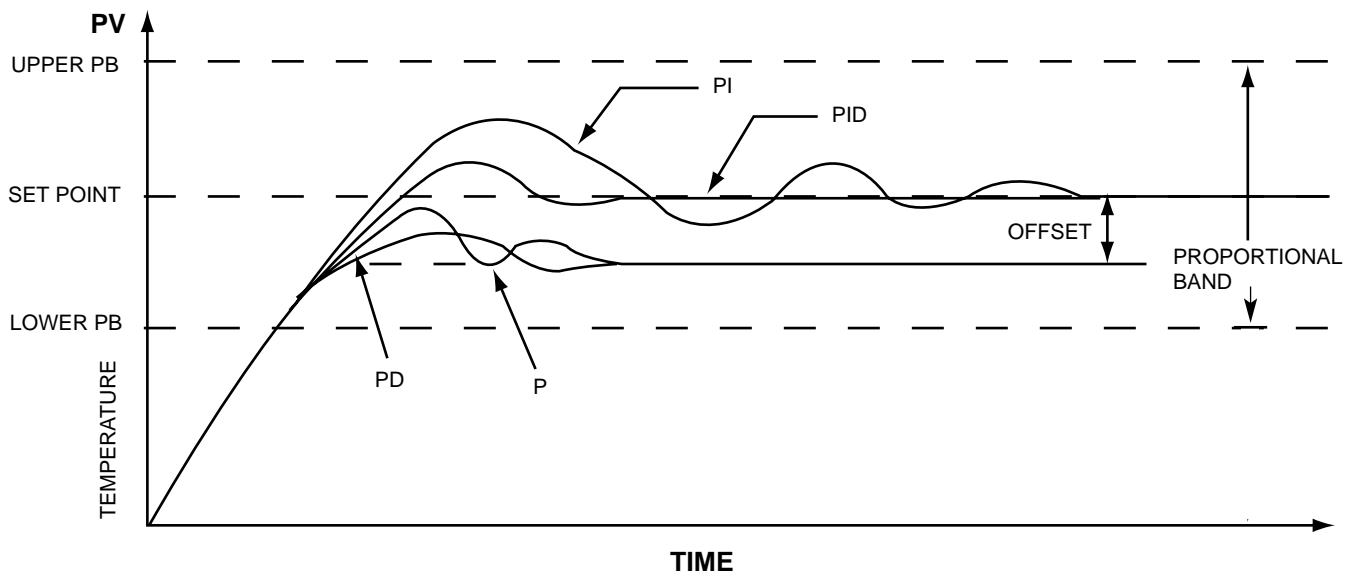
- Step 1: Adjust the integral and derivative values to 0. This inhibits the rate and reset action.
- Step 2: Set an arbitrary value of proportional band and monitor the control results.
- Step 3: If the original setting introduces a large process oscillation then gradually increase the proportional band until the oscillation disappears.
- Step 4: If the original setting does not introduce process

This method was developed by Ziegler and Nichols.

If you are unfamiliar with tuning PID Controllers, we suggest that you obtain and become familiar with the following reference material: *Tuning of Industrial Control Systems* by A.R. Corripio ISBN: 1-55617-253-2-Q. Available from: ISA Publications and Training Aids, Phone: 919-549-8411.

This method should be performed with a temperature chart recorder.

Fig. 5.4 Response of a Typical Control System Using Various Modes of Control



**Table 5.6 Tuning Guide**

ADJUSTMENT SEQUENCE:	SYMPTOM:	SOLUTION:
1.) Proportional Band	Slow Response	Decrease P Band (Pb)
	High Overshoot or Oscillations	Increase P Band (Pb)
2.) Integral Time (Reset)	Slow Response	Increase Reset (i.e. Decrease Integral Time)
	Instability or Oscillations	Decrease Reset (i.e. Increase Integral Time)
3.) Derivative Time (Rate)	Slow Response or Oscillations	Decrease Rate (i.e. Decrease Derivative Time)
	High Overshoot	Increase Rate (i.e. Increase Derivative Time)

### PID Control (Proportional, Integral, Derivative):

For various applications the controller can be used as P control only (set integral = 0, derivative = 0); PI control (set derivative = 0), PD control (set integral = 0), and PID control.

Figure 5.4, on page 18, represents the response of a typical control system using various modes of control.

- 1.) P control results in a response showing a deviation (offset), a high overshoot and a moderate period of oscillation. In addition, a significant length of time is required before the system ceases to oscillate.
- 2.) PI control has no offset, but elimination of offset comes at the expense of higher overshoot, larger period of oscillation and a longer time required for oscillations to cease compared with other modes of control.
- 3.) PD control generally brings the system to steady state in the shortest time with the least oscillation. However, it still has offset.
- 4.) PID control is essentially a compromise between the advantages of PI and PD control. Offset is eliminated by the integral action. The derivative action serves to lower offshoot and to eliminate some of the oscillations realized with PI control.

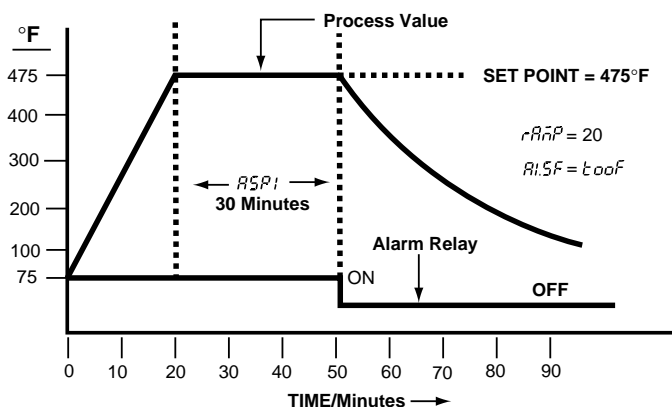
### Ramp and Soak Function:

The ETR-9200 can be programmed as a two segment ramp and soak control. The ramp rate, in degrees per minute, is determined by the "rRnSP" setting. The soak function is accomplished by configuring alarm 1 relay as a timer. The heater (or contactor coil) must be wired in series through the alarm 1 relay and the "out 1" relay. Refer to wiring diagram figure 4.9 on page 8. To use this

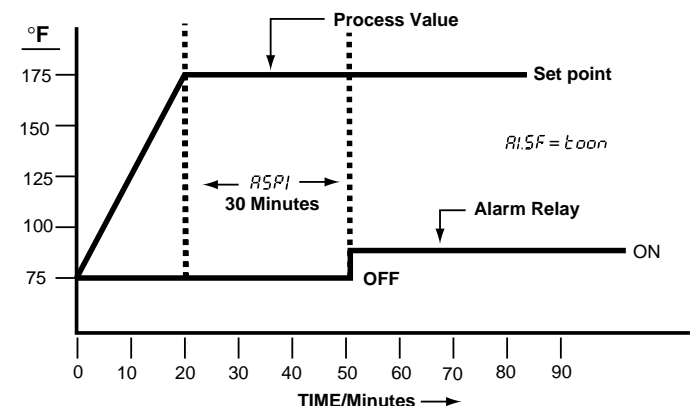
feature, set A1.SF (alarm 1 special function) to  $\text{tsooF}$ . Set the soak period at ASP1 (alarm 1 set point). The alarm relay will be closed at start-up. It will remain closed until the process temperature has remained at the set point temperature for the time period (minutes) set in ASP1. Note the following example: The ramp rate is set to 20 (degrees per minute), A1.SF is set to  $\text{tsooF}$  and ASP1 to 30 (minutes). When the control is powered, the process will climb at 20 degrees per minute to the set point of 475°F. Once the set point temperature has been reached, the soak timer begins counting. After a time period of 30 minutes has elapsed, the alarm relay 1 will open and the process temperature falls at an uncontrolled rate. This process will repeat every time power has been switched off and on to the controller. Note diagram 1 below.

### Single Event (Dwell) Function:

The single event (dwell) function may be used to control external devices such as lights, bells or locks. It could also be used to alert the operator when a guaranteed soak time has been reached. To use this feature, set ASP1 (alarm 1 set point) to the time period (in minutes) of the timer. Set A1.SF (alarm 1 special function) to  $\text{tsooN}$ . The alarm 1 relay will now operate as a timer. Refer to wiring diagram figure 4.10 on page 9. The alarm 1 relay will be open at start-up. Once the set point temperature has been reached and the time period set in ASP1 has elapsed, the alarm 1 relay will close. This relay will remain closed until power to the control has been disconnected. The cycle will repeat each time the control has been energized. Other features such as ramp rate and alarm 2 can also be used. Note diagram 2 below. The set point is 175°F and the dwell time has been set to 30 minutes.



**Diagram 1: Ramp and Soak**



**Diagram 2: Single Event**

Table 5.7

### Alarm Modes:

There are two independent alarms available. The alarm modes are selected by designating the alarm types with the parameter:  $A1.\bar{n}d$  and  $A2.\bar{n}d$ . The alarm special functions (  $A1.SF$  and  $A2.SF$  ) can be implemented together with the  $A1.\bar{n}d$  and  $A2.\bar{n}d$  modes that are selected.



: Alarm ON

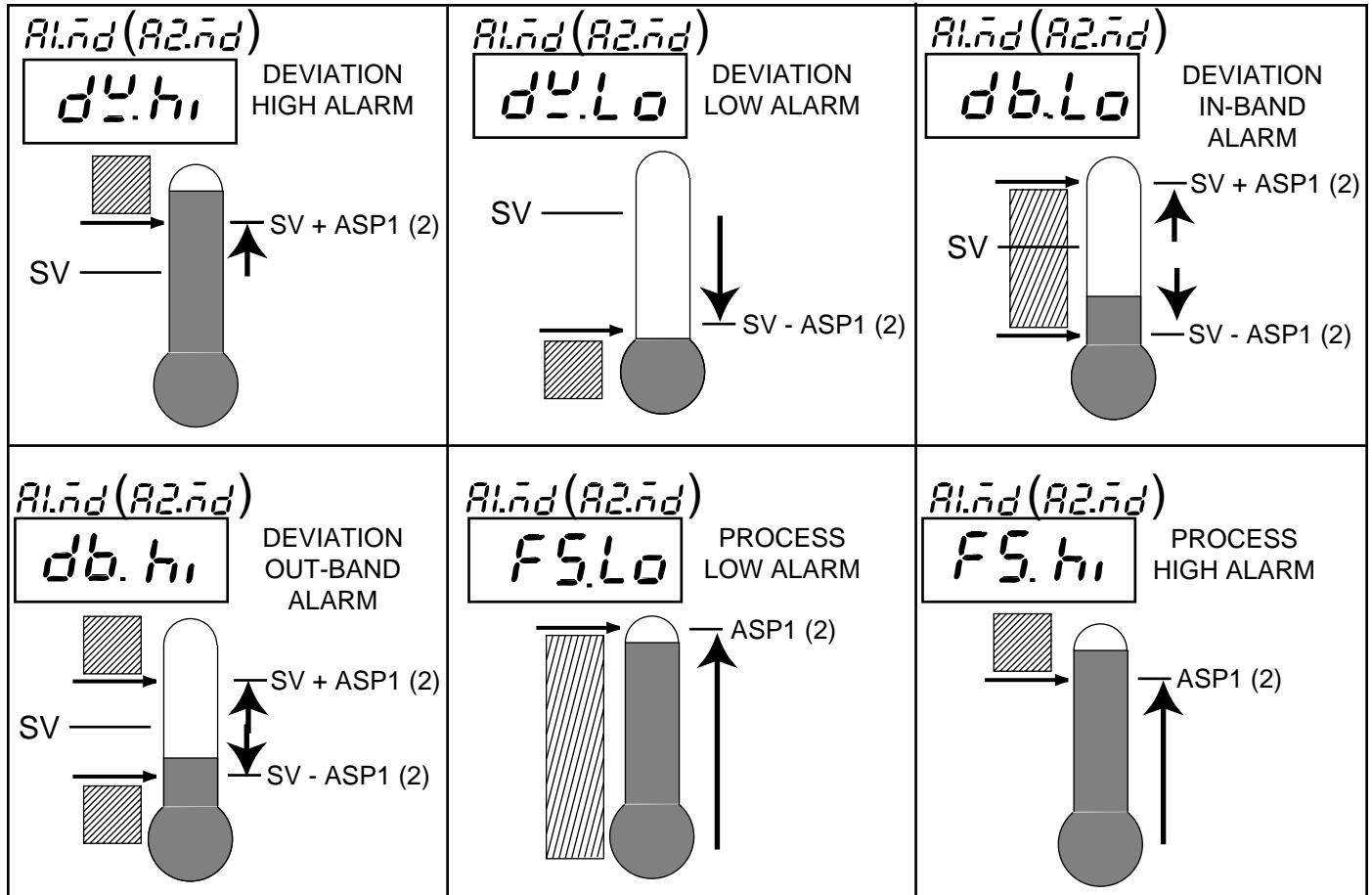
**SV = SETPOINT VALUE**

$ASP1$  = Alarm 1 Set Point

$ASP2$  = Alarm 2 Set Point

$A1.\bar{n}d$  = Alarm 1 Mode

$A2.\bar{n}d$  = Alarm 2 Mode



### • ALARM SPECIAL FUNCTIONS: A1.SF (A2.SF)

#### • Latch Alarm: A1.SF (A2.SF) = *latch*

When the latch mode is selected, the alarm will stay active until the power is reset.

#### • Inhibited Alarm: A1.SF (A2.SF) = *hold*

This mode prevents an alarm at start up. The alarm is enabled only when the Process Value reaches the Set Point (SV).

#### • Latch and Inhibited Alarm: A1.SF (A2.SF) = *latch*

When selected, the alarm will stay active until the power is reset. The alarm mode is only enabled when the Process Value reached the Set Point Value (SV).

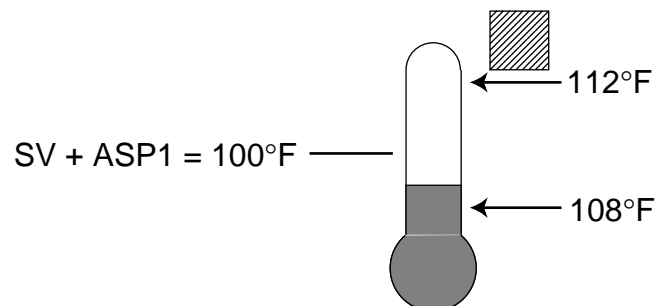
#### • Cooling: A2.SF = *cool*

Alarm 2 can be designated as a cooling output if heating and cooling operation is desired.

#### • Hysteresis (AHY1)

EXAMPLE: No special function used with (SV)  
Deviation High Alarm.

SV = 100°F ASP1 = 10°F AHY1 = 4°F



#### • Alarm Set Point Ranges

- Low scale ~ High scale (Full scale Alarms)
- -199 - 199°F (-111 - 111°C) Deviation alarms
- 0-9999 minutes for (A1.SF = *toon* or *toof*) Dwell Time

## Display Shift

In certain applications it is desirable to shift the controllers indicated value from its actual value. This can be easily accomplished with this control by using the display shift function. Cycle the control to the *SHIFT* parameter by using the "Scroll" pushbutton. The number you adjust here, either positive or negative, will be the amount that the process value (PV) will be shifted from the actual value. This amount will be the same across the entire range of the control. Note the example stated below.

The desired temperature at the part to be heated is 330 degrees F. In order to achieve that temperature, the controlled value or the temperature at the sensor must be 375 degrees F. Due to the design and position of the components of the system, the sensor could not be placed any closer to the work.

Thermal gradients (different temperatures) are common and necessary to an extent in any thermal system for heat to be transferred from one point to another.

The difference between the two temperatures is 45 degrees F. You should input -45 as to subtract 45 degrees from the actual process value (PV).

Cycle the control back to the process value after making this adjustment.

The display shift will alter the process value (PV) only.

The set point must be manually adjusted to 330.



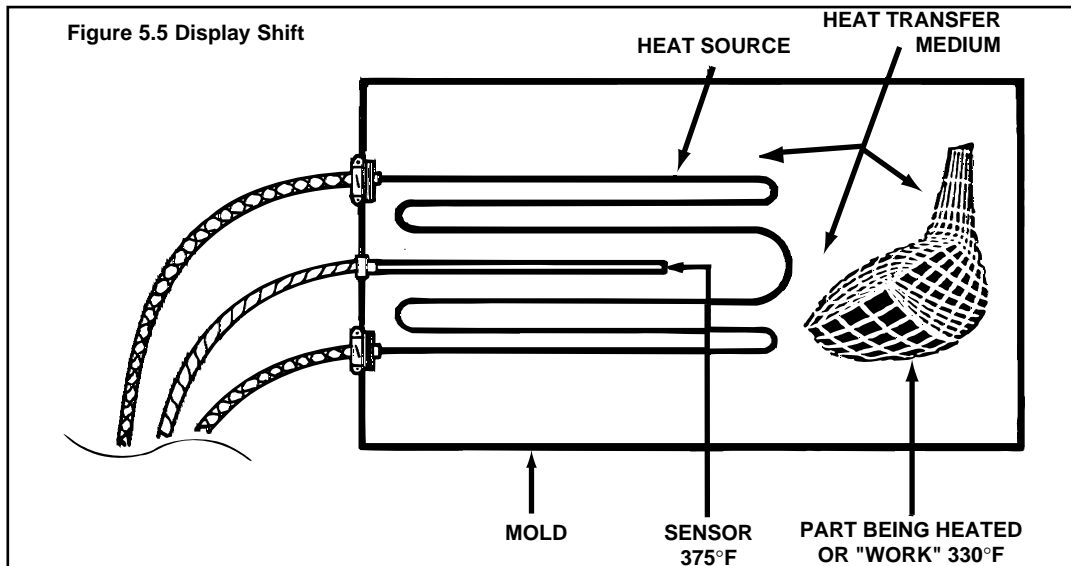
DISPLAY BEFORE  
INPUT SHIFT



DISPLAY AFTER INPUT SHIFT.  
ADJUST SV TO 330



DISPLAY AFTER INPUT SHIFT  
AND SV ADJUSTMENT



### DIRECTIONS FOR USING RETRANSMISSION (TRANSFER) OUTPUT:

The retransmission output of 4-20mA uses terminals #9 and 10. Terminal 9 is positive (+) and 10 is negative (—).

The interface parameter (Addr) is used to select which value is retransmitted. The possible selections are as follows:

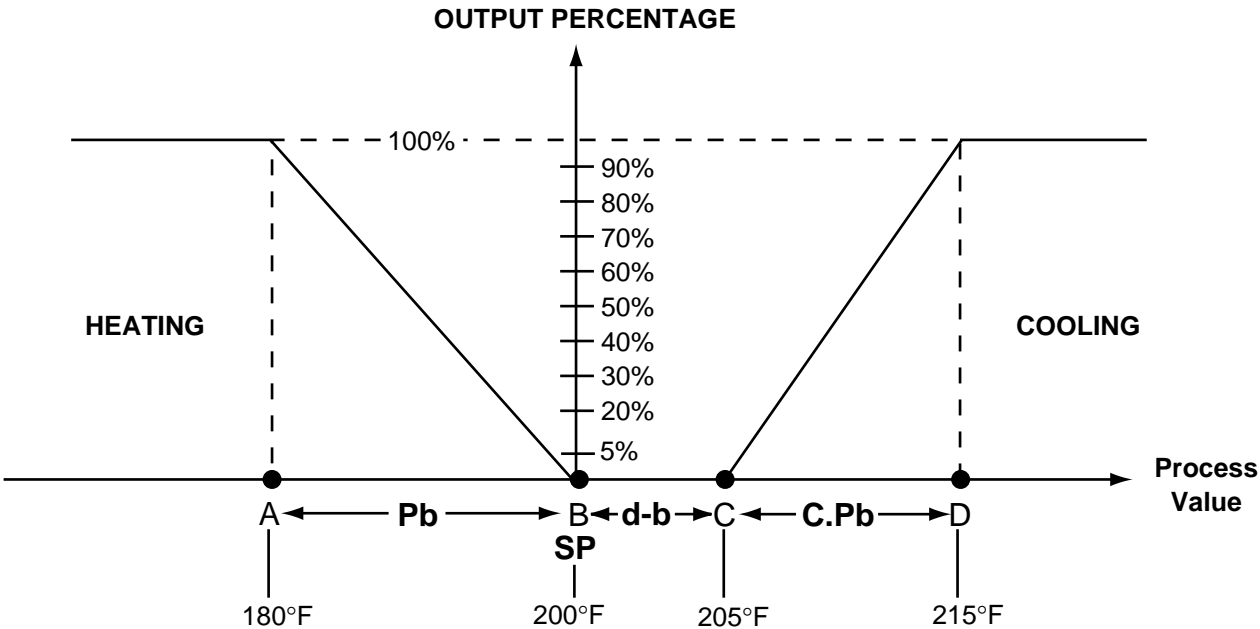
192	Retransmit Process Value, 4-20mA	196	Retransmit Process Value, 0-20mA
193	Retransmit Set Point Value, 4-20mA	197	Retransmit Set Point Value, 0-20mA
194	Retransmit Alarm Value 1, 4-20mA	198	Retransmit Alarm Value 1, 0-20mA
195	Retransmit Alarm Value 2, 4-20mA	199	Retransmit Alarm Value 2, 0-20mA

Set the span of the control, low scale (Lo.SC) and high scale (hi.SC) to set the span of the retransmitted output.

**FOR EXAMPLE: 0-1000, SPAN Lo.SC set to 0 and hi.SC set to 1000 would transmit 4MA AT 0 and 20MA at 1000.**

**Cooling Deadband Adjustment:**

This adjustment is used on the ETR-9200 to set the point at which the cooling set point is made. The heating proportional band, cooling proportional band and deadband are described in the following chart. Please note that Alarm 2 Special Function (A2.SF) must be set to cool.



- SP** = Set Point (SV)
- Pb** = Heating Proportional Band
- d-b** = Deadband
- C.Pb** = Cooling Proportional Band

The points on the chart are:  
**A** = SP - Pb  
**B** = SP  
**C** = SP + d-b  
**D** = SP + d-b + C.Pb

An example of the settings of a typical system may be:

- Set Point = 200°F
- Pb = 20°F
- C.Pb = 10°F
- d-b = 5°F

In this example the points on the chart would be:

- A = 180°F      SP - Pb = 200 - 20 = 180
- B = 200°F      SP
- C = 205°F      SP + d-b = 200 + 5 = 205
- D = 215°F      SP + d-b + C.Pb = 200 + 5 + 10 = 215

Increasing the deadband (d-b) setting will increase the span between the heating and cooling set points. The range of this adjustment is from -199 - 199°F (-111 - 111°C).

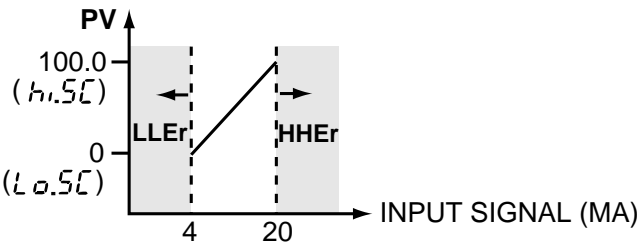
**Figure 5.6 Deadband Adjustment**

**Re-ranging for Linear Process Inputs:**

Select the type of input you wish to use from the *inPt* (input type) list in the operators menu on page 12. This would correspond to the output of the sensor or transmitter you are using. If the front display is to read in engineering units instead of temperature and if two decimal places are required, then change the *unit* (display units) setting to *Pu* (process units). In this setting, the "F" and "C" indicators on the control's face will not illuminate. Define the control's range by adjusting the low scale (*LoSc*) and high scale (*HiSc*) setting. Note the following example:

The input type has been set to 4-20mA and the span has been set to read 0-100. At 12mA input, the process

value will read 50. If the input signal goes beyond the range of the low and high limit, an error message (*LLEr* or *HHEr*) will be shown in the upper display. Note the correct input terminals on page 5 to use for the various types of sensors and transmitters.



## Section 6: CALIBRATION PROCEDURE

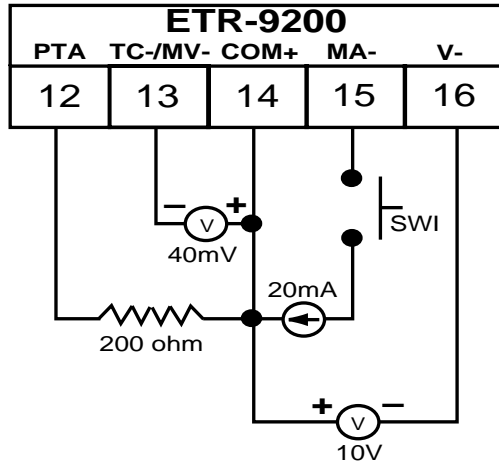
**WARNING!** *Do not attempt to recalibrate unless you are absolutely sure that the control needs to be recalibrated and that the proper equipment is available. Once this is preformed, all other calibration information will be lost!*

### Equipment Needed:

- 1) Standard millivolt power source range 0-100mV, accuracy  $\pm 0.01\%$
- 2) Standard voltage power source range 0-10V, accuracy  $\pm 0.01\%$
- 3) Standard current power source range 0-20mA, accuracy  $\pm 0.01\%$
- 4) Standard ohm source range 0-300 ohm, accuracy  $\pm 0.01\%$
- 5) Standard thermometer range 0-50.0°C, accuracy  $\pm 0.2^\circ\text{C}$
- 6) A cooling fan may be needed to keep equipment cool
- 7) Thermocouple simulator
- 8) Pushbutton switch

### Calibration Set-up:

- 1) Select Input type to J T/C, UNIT = C, RESO = 1dp
- 2) Turn power OFF
- 3) Disconnect all wiring
- 4) Connect wiring as shown below:

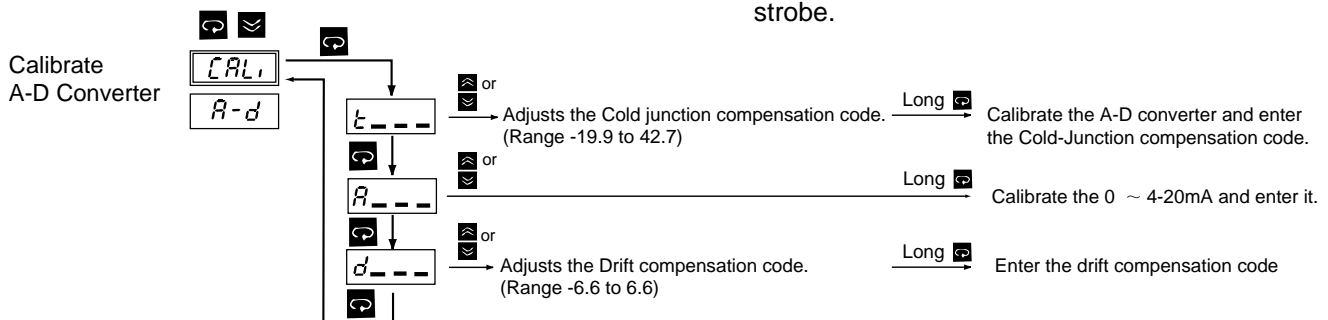


- 5) A fan should be used to keep the cold junction compensator cool. (Lower PCB rear)

### Calibration Steps:

- 1) Enter the "Engineering Level" by pressing the and keys simultaneously. Continue to press these keys until is displayed. (See flow chart below.)
- 2) Press the key to view .
- 3) Use the and keys to enter the room temperature on the upper display in degrees °C. Once the proper room temperature is entered, press the key for 4 seconds. After the key is released, the upper display will strobe, indicating that the new value has been loaded into the memory.
- 4) Press the key to view .
- 5) The upper display should read 0.00. Close SW1. The upper display should now read 20.00. If the value is not 20.00, make sure that the current source is accurate. After a value of 20.00 is displayed in the upper display, then the key should be pressed for 4 seconds. After the key is released, the upper display will strobe. This indicates that the new value is properly entered into the controller memory.
- 6) Press the key to view .
- 7) The lower display should be 0.00. If it isn't, change the value using the and keys. After 0.00 has been obtained, press the key for 4 seconds. When the key is released, the upper display will strobe. This indicates that the new value has been properly entered into the memory. If the value was 0.00, there is no need to load the information into the memory again.
- 8) Remove all connections. Now connect a thermocouple simulator across terminals 13 and 14 and check calibration (controller must be powered for 30 minutes). If a different input is used, check that input also. If the temperature is incorrect, perform steps (2) and (3) above.
- 9) If the controller is still not accurate the drift must be adjusted. Enter the Engineering Level and go to . Press the key until is displayed. Use the and keys to enter the correction factor that will be shown in the lower display. This number will be added or subtracted from the upper display. Once the values are correct, press the key for 4 seconds. This will load the new value into the memory. If the value is successfully entered into the memory, the upper display will strobe.

### ENGINEERING LEVEL





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## Section 7: TROUBLESHOOTING

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**WARNING!** THIS PROCEDURE REQUIRES ACCESS TO THE CIRCUITRY OF A LIVE POWER UNIT. DANGEROUS ACCIDENTAL CONTACT WITH LINE VOLTAGE IS POSSIBLE. ONLY QUALIFIED PERSONNEL ARE TO PERFORM THESE PROCEDURES. POTENTIALLY LETHAL VOLTAGES ARE PRESENT.

Experience has proven that many control problems are not caused by a defective instrument. See chart below and Table 7.1 on the next page for some of the other common causes of failures:

Incorrect parameters entered in menu.

Excessive electrical interference.

Line wires are improperly connected.

No voltage between line terminals.

Incorrect voltage between line terminals.

Connections to terminals are open, missing or loose.

Thermocouple (or RTD) is open at tip.

Thermocouple (or RTD) lead is broken.

Shorted thermocouple (or RTD) leads.

Short across terminals.

Open or shorted heater circuit.

Open coil in external contactor.

Burned out line fuses.

Burned out relay inside control.

Defective solid-state relays.

Defective line switches.

Burned out contactor.

Defective circuit breakers.

If the points listed on the chart have been checked and the controller does not function, it is suggested that the instrument be returned for inspection.

Do not attempt to make repairs. Also, it is advisable to use adequate packing materials to prevent damage in shipment.

Return control to:

**OGDEN MANUFACTURING COMPANY**  
ATTN: REPAIR DEPARTMENT  
64 WEST SEEGER'S ROAD  
ARLINGTON HEIGHTS, IL 60005

**1)** Press latches on each side to remove rear terminal block.

**2)** To remove PCB assembly from housing, insert two small screw drivers between the PCB and housing top and bottom. This will expand the housing and release the locking tabs. Then pull the PCB assembly out of the housing.



Table 7.1 Troubleshooting

Symptom	Probable Cause(s)	Solution(s)
1.) LED's will not light.	—No power to instrument.	—Check power line connections.
	—Power supply defective.	—Replace power supply board.
2.) Some segments of the display or LED lamps not lit or lit erroneously.	—LED display or LED Lamp defective.	—Replace LED display or LED lamp.
	—Related LED driver defective.	—Replace the related transistor or IC chip.
3.) Process Display shows: <i>5bEr</i>	—Sensor break error.	—Replace RTD or sensor. —Use manual mode operation.
4.) Process Display shows: <i>LLEr</i>	—Process value beyond the low range setpoint.	—Re-adjust <i>LLiE</i> value.
5.) Process Display shows: <i>HLEr</i>	—Process value beyond the high range setpoint.	—Re-adjust <i>HLiE</i> value.
6.) Process Display shows: <i>REr</i>	—Analog hybrid module damage.	—Replace module. Check for outside source of damage such as transient voltage spikes.
7.) Process Display shows: <i>REr</i>	—Incorrect operation of auto tune procedure. Prop. Band set to 0.	—Repeat procedure. Increase Prop. Band to a number larger than 0.
8.) Process Display shows: <i>oPEr</i>	—Manual mode is not allowable for an ON-OFF control system.	—Increase proportional band.
9.) Process Display shows: <i>ESEr</i>	—Check sum error, values in memory may have changed accidentally.	—Check and reconfigure the control parameters.
10.) Display Unstable	—Analog portion or A-D converter defective.	—Replace related components or board.
	—Thermocouple, RTD or sensor defective.	—Check thermocouple, RTD or sensor.
	—Intermittent connection of sensor wiring	—Check sensor wiring connections.
11.) Considerable error in temperature indication.	—Wrong sensor or thermocouple type. Wrong input mode selected.	—Check sensor or thermocouple type and if proper input mode was selected.
	—Analog portion A-D converter defective.	—Replace related components or board.
12.) Display goes in reverse direction (counts down scale as process warms).	—Reversed input wiring of sensor.	—Check and correct.
13.) No heat or output	—No heater power (output), incorrect output device used.	—Check output wiring and output device.
	—Output device defective.	—Replace output device.
	—Open fuse outside of the instrument.	—Replace output fuse.
14.) Heat or output stays on but indicator reads normal.	—Output device shorted, or power service shorted.	—Check and replace.
15.) Control abnormal or operation incorrect.	—CPU or EEPROM (non-volatile memory) defective. Key switch defective.	—Check and replace.
	—Operation of control incorrect.	—Read the operation procedure carefully.
16.) Display blinks, entered values change by themselves.	—Electromagnetic interference (EMI), or Radio Frequency Interface (RFI).	—Suppress arcing contacts in system to eliminate high voltage spike sources. Separate sensor and controller wiring from “dirty” power lines, ground heaters.
	—EEPROM defective.	—Replace EEPROM.